

31 **1. INTRODUCTION**

32 Wind energy is one of the most used green sources of electricity and has become popular as
33 the wind is reliable and freely available [1]. Approximately 10 GW of electricity is produced
34 from offshore wind, and combined offshore and onshore wind farms can provide power for
35 more than 18 million homes every year in the UK. It is expected that over 10% of UK electricity
36 will be generated from offshore wind in the next few years. To meet the increasing energy
37 demand, the sizes of wind turbines are being increased to capture the wind more effectively
38 and efficiently [2]. Although innovative technologies and advances in wind turbines play a
39 vital role in the success of the wind energy industry, the design and optimisation of wind farms
40 are challenging for the industry in order to maximize the energy captured as well as the power
41 generation [3,4]. A wind farm consists of a number of large-capacity wind turbines and
42 therefore, the flow around a turbine is expected to be influenced by the wakes from
43 neighbouring turbines [5]. Among several factors to design and optimise a wind farm layout,
44 the determination of separation distance between adjacent turbines is very crucial to minimize
45 the influence of the wake deficits and turbulence from the upstream wind turbine and to
46 maximize the power output of the downstream turbine [6]. Therefore, the wake calculation and
47 prediction are of utmost importance to identify the effects associated with neighbouring wind
48 turbines for the optimisation of the wind farm layout.

49
50 Ideally, the prediction of aerodynamic performances of wind turbines should be carried out or
51 validated through full-scale experiments to achieve accurate results. While full-scale wind
52 turbine experiments are not practically feasible, various small-scale experiments were
53 conducted and reported in the literature [7-12]. Although researchers have control of inflow
54 conditions or boundary conditions in the wind tunnel experiments, these experiments still
55 impose uncertainties while reproducing the environmental conditions in which wind turbines

56 are operated [13]. Therefore, the flow unsteadiness associated with these physical key factors
57 is ignored in the wind tunnel experiments. Furthermore, the scaling effect encountered with the
58 small-scale experiments should also not be neglected.

59

60 With all the advances in computing and technology, several numerical modelling and solution
61 methods are now available for analysing the aerodynamics of wind turbines. Modern wind
62 turbines are designed based on wind turbine specialist codes based on the Blade Element
63 Momentum (BEM) theory [14]. The BEM models are typically used for the prediction of
64 aerodynamic loads in the initial stage of the design process of wind turbine rotors and blades.
65 However, the accuracy of the prediction depends on the availability of the aerofoil data for the
66 lift and drag coefficients. The advantage of BEM models is computationally fast and reasonable
67 results can be obtained provided that adequate aerofoil data are available. However, flow
68 details, which is important for the aerodynamics of wind turbines, cannot be obtained with
69 BEM models. Therefore, wind tunnel experiments or high-fidelity numerical methods are still
70 required and usually employed in the later stage of the design process of wind turbines in order
71 to understand the flow behaviour. The vortex models employing prescribed-wake methods or
72 free-wake methods are also applied to the analysis of aerodynamics and wake structures of
73 wind turbines. Lee et al. [15] used an unsteady vortex-lattice method to study the aerodynamic
74 performance and wake structures of a wind turbine. Riziotis et al. [16] and Jeong et al. [17]
75 applied a free-wake model to study the aerodynamics and aeroelasticity of wind turbine blades
76 under different conditions. Rodriguez et al. [18,19] employed a vortex model for the
77 aerodynamic analysis of offshore wind turbines. The viscous effects, however, are neglected
78 by most vortex models. The actuator type models in which the wind turbine rotor or blades are
79 represented by a disk or a line model with variable load distributions, known as the actuator
80 disk model or actuator line model, are also used in the wind turbine aerodynamic analysis.

81 Sorensen et al. [20] used the actuator disk model to analyse the turbulent wake and vortex states
82 of a wind turbine rotor whereas Troldborg et al. [21] applied the actuator line model to the
83 simulation of a wind turbine operating in the turbulent wake. These methods can be combined
84 with Navier-Stokes equations replacing the rotor or the blade with an actuator disc or line with
85 distributed loads. However, the loads on the rotor or the blade are calculated based on the BEM
86 theory and the accuracy of the simulation depends on the calculation of the aerodynamic loads.
87 In addition, the computational costs required by these methods are higher than BEM models
88 [22].

89

90 Computational Fluid Dynamics (CFD) methods can resolve the flow structures and boundary
91 layers without requiring the load prediction on the blade surfaces or aerofoil data beforehand.
92 Recently, CFD methods are used in the wind energy industry to analyse as well as optimise
93 aerodynamic performances of wind turbines [23-25]. Lin et al. [26] and Dose et al. [27] used a
94 CFD model to calculate aerodynamic loads on a wind turbine blade or rotor whereas Yu et al.
95 [28] and Dose et al. [29] employed a CFD method to perform an aerodynamic analysis of a
96 complete wind turbine model including a tower and predicted flow structures. CFD methods
97 have also been applied to simulations of multiple wind turbines. Allah et al. [30] and Ciri et al.
98 [31] conducted aerodynamic simulations of two in-line wind turbines and analysed the wake
99 behaviour. Choi et al. [32] performed CFD simulations of two wind turbines by varying the
100 separation distance between turbines. Moreover, Korobenko et al. [33] proposed a multi-
101 domain method to perform simulations of two back-to-back wind turbines. The main
102 disadvantage of the CFD methods is their large computational resources requirement.
103 Significant computational resources and long runtimes are typically required for the unsteady
104 computations, especially when multiple wind turbines are involved.

105

106 In the field of turbomachinery analysis, numerical studies have been conducted to develop
107 efficient numerical methods which can reduce the computational cost without compromising
108 accuracy in predicting unsteady flows. Frequency domain methods such as the harmonic
109 balance method of Hall et al. [34], the phase solution method of He [35], and Rahmati et al.
110 [36,37] have been developed and widely used in the turbomachinery analysis due to their
111 capabilities of modelling harmonic disturbances and flow nonlinearities at a reasonable
112 computational cost. It is also important to ensure that frequency domain methods can predict
113 the flow structures accurately when highly unsteady flows are involved. High-resolution direct
114 numerical simulations of the transitional flow structures around an aerofoil provides interesting
115 and detailed vortex structures [38,39]. The capability of a frequency domain method on
116 capturing these highly unsteady flow structures in a modern low-pressure turbine was also
117 investigated by Shine et al. [40] by means of direct numerical simulation and it is found that it
118 has the capability of predicting complex and highly unsteady flows.

119

120 Recently, frequency domain methods have also been applied to the aerodynamic and
121 aeroelasticity analysis of wind turbines [41,42]. Shine et al. [43] proposed a nonlinear
122 frequency domain solution method to analyse the effect of inflow turbulence and wake on both
123 aerodynamics and aeroelasticity of wind turbine rotors, and also investigated the effect of
124 material properties on the aerodynamic damping of the blade based on a relatively high
125 amplitude of vibration. It appears that the inflow wake influences the flow field around the
126 wind turbine, and it has an impact on both aerodynamics and aeroelasticity of the wind turbine
127 blade. They later extended their study to carry out an aeromechanical analysis of a complete
128 wind turbine model including a tower using a nonlinear frequency domain solution method
129 [44]. Rahmati et al. [45] developed a nonlinear frequency domain solution method for the
130 aeroelasticity analysis of multiple blade row configurations. It is found that a fully coupled

131 multiple blade row model yields higher accuracy in predicting the flow behaviour of the
132 turbomachines than the simplified isolated one [46]. This has motivated the authors to approach
133 differently by considering wind turbines in arrays as a multi-stage turbine so that the frequency
134 domain method can be applied to perform the rotor-stator interactions and the aerodynamic
135 simulations of multiple turbines at an affordable computational cost.

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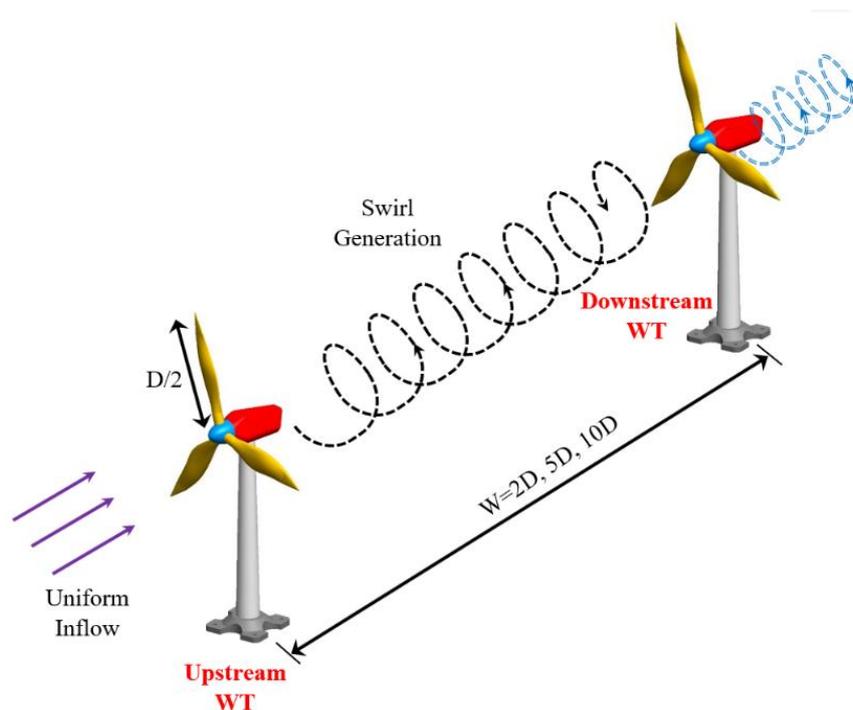
137 It is clear from this above literature review that, while high-fidelity CFD simulations of the
138 multiple wind turbines are important, the conventional time domain solution methods are
139 impossible or difficult to be performed due to the high computational demand. On the other
140 hand, it was revealed that frequency domain solution methods can provide accurate results with
141 significantly lower computational cost compared to conventional time solution methods.
142 Therefore, a novel nonlinear frequency domain solution method is proposed to model and study
143 wind turbine in arrays in this study. In this paper, wind turbines in arrays will be modelled in
144 multi-row configurations and the distance between the upstream turbine and the downstream
145 one will be varied. The considered distances between the turbines are 2D, 5D and 10D, where
146 D is the rotor diameter, and the effects of the upstream wind turbine on the downstream one
147 will be investigated. This is the first time that a frequency domain method is applied to the
148 investigation of multiple wind turbines. The main distinctive feature of this paper is the
149 modelling of wind turbines in arrays as a multi-stage turbine and the application of the
150 frequency domain solution method, which reduces the computation time significantly to a
151 reasonable and affordable level.

152

153 **2. PHYSICAL DESCRIPTION**

154 Figure 1 shows the schematic view of two wind turbines in arrays with different distances in
155 the present study. The MEXICO (Model Rotor Experiments In Controlled Conditions)

156 Experiment wind turbine model was experimentally tested and studied in a wind tunnel in the
157 Large-Scale Low-Speed Facility of the German-Dutch Wind Tunnel (DNW) [7-10]. There are
158 various numerical studies which have been conducted using this wind turbine model [47-50].
159 In this paper, the MEXICO-Experiment wind turbine model is modified to model the wind
160 turbines in arrays by adding another rotor behind the first wind turbine. Each wind turbine has
161 three blades, and the blade is 2.04 m long. The rotor diameter, D , is 4.5 m. The separation
162 distance between the turbines in the axial direction (W) is defined in terms of rotor diameter,
163 D , and the considered distances between the turbines are $2D$, $5D$ and $10D$ in this study. To
164 evaluate the effects of wind turbines in arrays on the flow behaviour and to analyse the
165 aerodynamic performances of the wind turbines, the design condition from the experiment
166 which corresponds to the wind speed of 15 m/s, the rotational speed of 424.5 RPM and the
167 design pitch angle of -2.3 degrees are used in this study. Both upstream and downstream wind
168 turbines are kept at the same rotational speed.
169



170
171 Figure 1. Schematic view of the two wind turbines in arrays with different separation distances
172

173 **3. NUMERICAL METHODOLOGY**

174 **3.1. Computational Method**

175 **3.1.1. Governing Equations**

176 In the present work, a three-dimensional density-based finite volume solver is employed for
177 the flow computation. The simulations are performed based on the URANS model. The flow
178 is governed by the Navier-Stokes equations and it can be expressed as:

179

180
$$\frac{\partial}{\partial t} \int_{\Omega} U d\Omega + \int_S \vec{F}_I \cdot d\vec{S} + \int_S \vec{F}_V \cdot d\vec{S} = \int_{\Omega} S_T d\Omega \quad (1)$$

181

182 where Ω is the volume, S is the surface, U is the vector of the conservative variables, S_T is the
183 source term, and \vec{F}_I and \vec{F}_V are the inviscid and viscous flux vectors, respectively. Spalart–
184 Allmaras turbulence model is employed in this work and the above equation can be simply
185 written in a semi-discrete form as [43-46]:

186

187
$$\frac{\partial}{\partial t} (U) = R(U) \quad (2)$$

188

189 where R is the lumped residual and the source term.

190

191 **3.1.2. Frequency Domain Solution Method**

192 In this study, the sources of the flow unsteadiness are associated with the flow interaction in
193 the multiple row configurations (i.e., the interaction between the rotor, tower (stator) and rotor).

194 The unsteady terms corresponding to the flow unsteadiness can be represented by a Fourier
195 series for a prescribed fundamental frequency, ω , and the specified number of harmonics, m ,
196 as expressed in Eq. (3).

197

198
$$U = \bar{U} + \sum_{m=1}^M [U_A \sin(m\omega t) + U_B \cos(m\omega t)] \quad (3)$$

199

200 where \bar{U} , U_A , and U_B are the Fourier coefficients of the conservative variables. The accuracy
201 of the unsteady solution can be controlled through the order of the Fourier series. In this paper,
202 as the source of flow unsteadiness is related to the flow interaction between the rotor and the
203 tower which is periodic in time, the fundamental mode (one harmonic) is considered enough
204 to resolve the flow. The blade passing frequency is the fundamental frequency of the system.
205 Substituting Eq. (3) into Eq. (2) yields the following equations.

206

207
$$\omega \sum_{m=1}^M [mU_A \cos(m\omega t) - mU_B \sin(m\omega t)] = R \quad (4)$$

208

209 These new set of unsteady Navier-Stokes equations are solved in the frequency domain with
210 the frequency domain method. With this method, the unsteady period for one complete rotor
211 rotation is equally divided into $N = (2m+1)$ time levels and the system of nonlinear equations
212 coupling all N time levels are then solved iteratively. After completion of the flow simulation,
213 the frequency domain solution can be reconstructed in time to have a flow solution in time
214 history, which can be directly compared to the time domains solution. A central scheme is used
215 for the spatial discretization and a four-stage explicit Runge–Kutta scheme is used for the
216 temporal discretization. Detailed formulation and implementation of the frequency domain
217 solution method can be found in [43-46].

218

219 **3.1.3. Rotor-Stator Interaction**

220 The relative motion between successive rows of rotating and stationary domains such as rotor
221 and tower is the main source of flow unsteadiness that affects the flow around the wind turbines
222 in arrays. In this study, a rotor-stator interface is employed to exchange the flow solution

223 between the rotating domain which includes a rotor and the stationary domain which includes
224 a tower. The task of the rotor-stator interface is to match the flow solution between the upstream
225 and downstream sides and to ensure the continuity of the unsteady flow across the interface.

226

227 The rotor-stator interface must be defined in the mesh generator after the mesh for each domain
228 has been generated. The boundaries from the upstream domain and the downstream domain
229 are connected using a full non-matching interface type, which allows to connect the grids with
230 several blocks with non-matching boundaries. It means that the grid boundaries with different
231 pitch lengths (i.e., rotational periodicity) can be connected. After connecting all grids together
232 and defining the rotor-stator interface, a single grid file is imported into the flow solver where
233 the rotor-stator interaction is set up, which indicates the flow direction, typically from the
234 upstream to downstream direction. But the flow interaction between the rotor and stator is taken
235 into account by transferring and exchanging the flow data between the two domains.

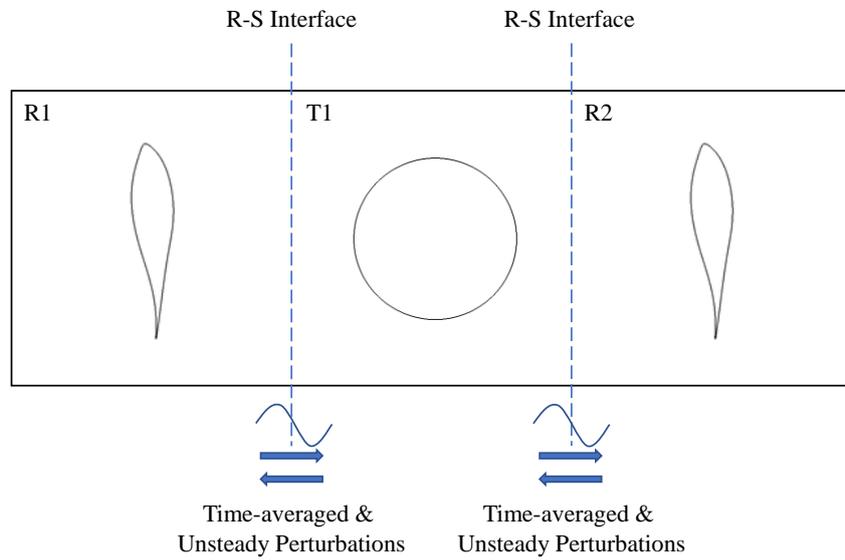
236

237 The standard sliding-plane method which is a time-accurate solution is applied for the time
238 domain solution. In this method, by using a direct local interpolation method, the instantaneous
239 flow information is exchanged across the interface at each time step. This method requires the
240 same rotational periodicity on both sides, which means a full wheel of the rotor and the stator
241 (both 360-degree grids) are required.

242

243 With a frequency domain solution method, on the other hand, the conservative flow variables
244 can be decomposed into a time-averaged value and unsteady perturbations for a specified m
245 harmonics, based on Fourier decomposition of the unsteady flow as expressed in Eq. (3). The
246 equality of rotational periodicity is obtained through the phase-shift periodicity as the harmonic
247 components are phase-shifted between periodic boundaries as explained in the next section.

248 Hence, the interaction between the rotor and the stator (i.e., the tower in this study) can be
 249 modelled by computing the time-averaged flow and the unsteady perturbations from the two
 250 adjacent rows and transferring the flow characteristics between the upstream row and the
 251 downstream row to ensure the continuity of the unsteady flow across the rotor-stator interface.
 252 The resolution and the continuity of the flow can be controlled through the order of Fourier
 253 series or the number of harmonics. More details of rotor-stator interface treatments can be seen
 254 in [36,37] and the applications of rotor-stator interfaces in the analysis of multi-stage turbines
 255 can be found in [45,46]. The schematic view of the rotor-stator interaction is shown in Fig. 2.



256
 257 Figure 2. Schematic diagram of the rotor-stator interaction between the wind turbines in arrays.
 258 (*R1: Rotor of the upstream wind turbine; T1: Tower of the upstream wind turbine; R2: Rotor*
 259 *of the downstream wind turbine*)
 260

261 **3.2. Boundary Conditions**

262 The solid wall boundary condition is applied on the blade, the hub and the tower. The external
 263 boundary condition, which is a non-periodic one, is defined to treat the far-field boundaries
 264 dealing with the external flow computations. A rotor-stator interface is used to connect the
 265 outflow surface of the rotor domain of the first wind turbine and the inflow surface of the rotor
 266 domain of the first wind turbine. The same interface type is used to connect the outflow surface

267 of the tower domain of the first wind turbine and the inflow surface of the rotor domain of the
268 second wind turbine. For the periodic boundaries of the rotor, the direct periodic (repeating)
269 condition is applied for the time domain method whereas only a single passage domain is
270 required for the frequency domain solution method. With the frequency domain method, the
271 harmonic components are phase-shifted between the periodic boundaries by a given Inter Blade
272 Phase Angle (IBPA), σ , defined by the number of blades available in a rotor, and it is expressed
273 in the following equations where the subscript 1 and 2 are corresponding to the referenced
274 passage and its neighbouring one, respectively [43-46].

275

$$276 \quad U_{A,2} = U_{A,1} \cos(\sigma) - U_{B,1} \sin(\sigma) \quad (5.a)$$

$$277 \quad U_{B,2} = U_{A,1} \sin(\sigma) + U_{B,1} \cos(\sigma) \quad (5.b)$$

278

279 **3.3. Computational Domain and Grid Generation**

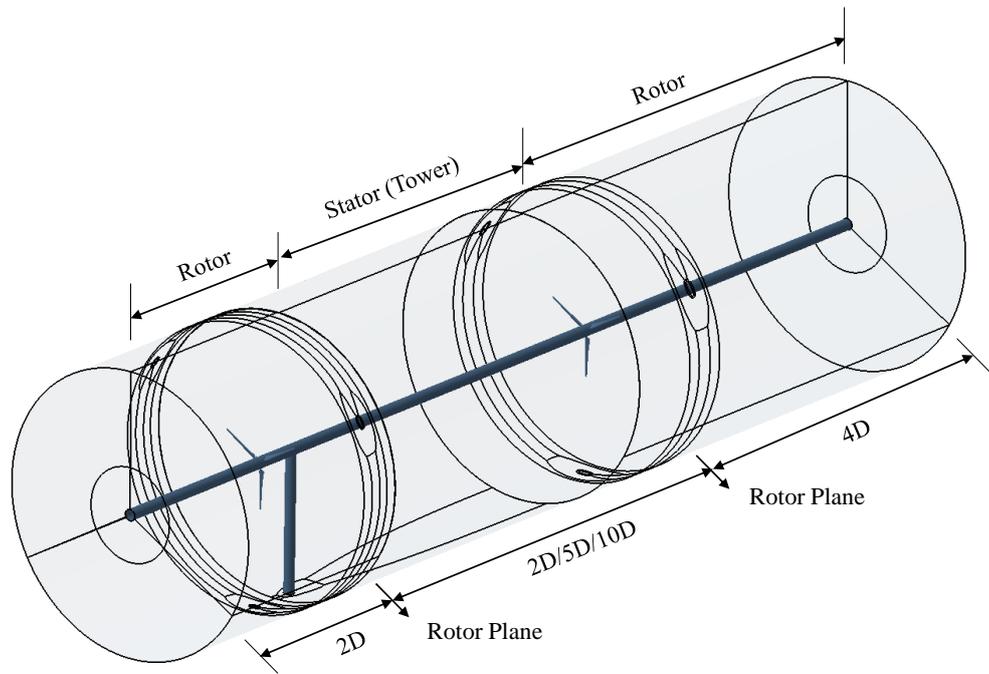
280 A new type of modelling method to simulate multiple wind turbines is proposed in this paper.
281 Wind turbines in arrays can be modelled in a multiple-row configuration considering as a multi-
282 stage turbine. In this study, there are two wind turbines in arrays, separated by a separation
283 distance. In terms of modelling, ideally, there should be a rotor model and a tower model from
284 each wind turbine. However, as this study investigates the effect of the upstream wind turbine
285 on the aerodynamic performances of the blades of the downstream turbine, only the rotor model
286 of the downstream turbine without the tower is included in the wind turbine in arrays model to
287 reduce the computation time. However, using the proposed method, a series of turbines can
288 further be modelled by adding more rotors and stators (i.e., towers). In order for the rotor-stator
289 interface to work effectively for the flow continuation, all rotor blades and stator blades (i.e.,
290 tower in this model) have to be on the same hub. Therefore, an infinitely long hub is used in
291 this paper to connect the rotors and the tower. An infinitely long hub was also employed in the

292 simulation of wind turbines before [51] and it is assumed that the effect of the hub on the flow
293 field around the wind turbines is not significant.

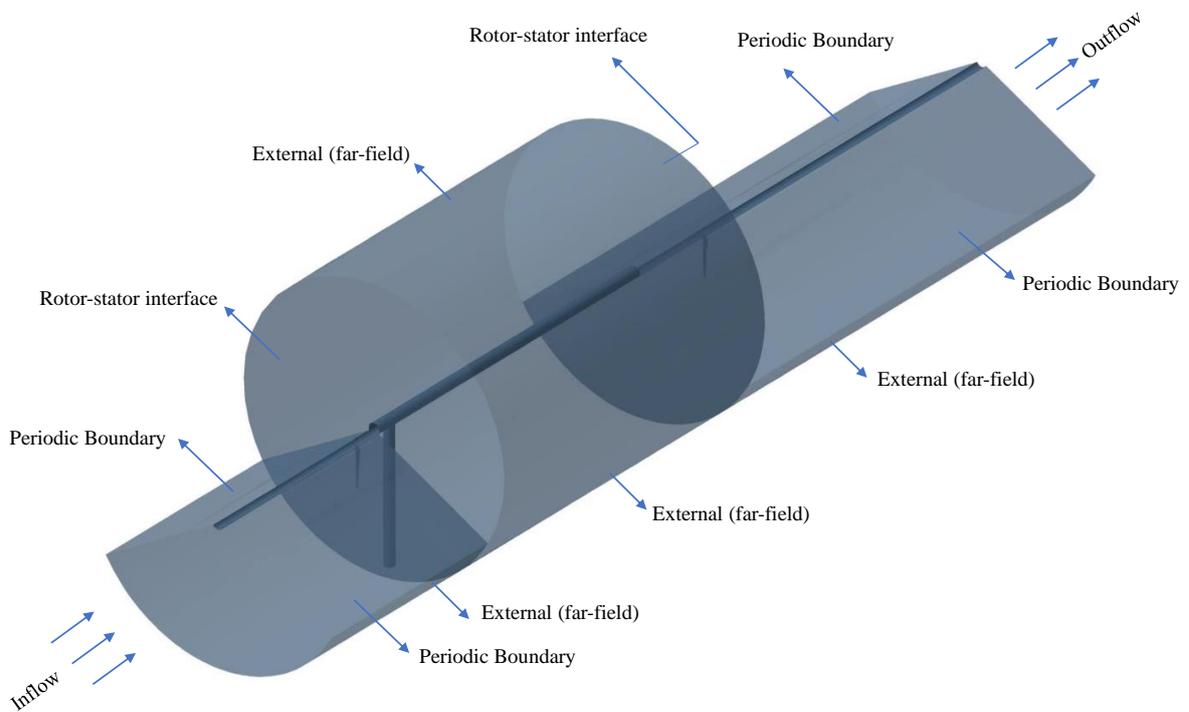
294

295 A structured grid generator is used to generate a three-dimensional computational domain and
296 grid. In order to model wind turbines in arrays, the rotors and the tower are meshed separately,
297 and they are connected through a rotor-stator interface. A Rounded Azimuthal O4H topology
298 is used for the generation of both rotor and tower grids. Each grid consists of five blocks such
299 as the skin block surrounding the blade, the inlet block located upstream of the leading edge,
300 the outlet block located downstream of the trailing edge, the upper block located above the
301 blade section, and the lower block located under the blade section. An O-mesh is used for the
302 skin block whereas an H-mesh is used for the remaining blocks. The frequency domain solution
303 method only requires modelling of a single passage or a single blade of a full rotor wheel,
304 which is one of the main advantages of this method for the analysis of turbomachines with
305 multiple blade rows. Using the frequency domain solution method, the harmonic components
306 of the flow variables can be phase-shifted between periodic boundaries by a given an inter
307 blade phase angle, as expressed in the boundary conditions section. Therefore, a 120-degree
308 grid is only required for the rotor model for the frequency domain solution (see Fig. 3 (b)). On
309 the other hand, the time domain solution method requires a full wheel of rotor and stator with
310 all blades for the time-accurate solution. Figure 3 (a) shows the overall view of the
311 computational domain including all three blades and tower. This is, in fact, the domain used
312 for the time domain solution. A 360-degree grid is generated for the tower domain. The flow
313 inlet and outlet are located 2D upstream of the rotor and 4D downstream of the rotor,
314 respectively, and the far-field boundary is placed 1.5D from the origin of coordinates, where
315 D is the rotor diameter. The first cell layer thickness is $1e-5$ meters to ensure that the y^+ value
316 is less than one. The generated grid consists of 4.5 million grid points in each of the rotor

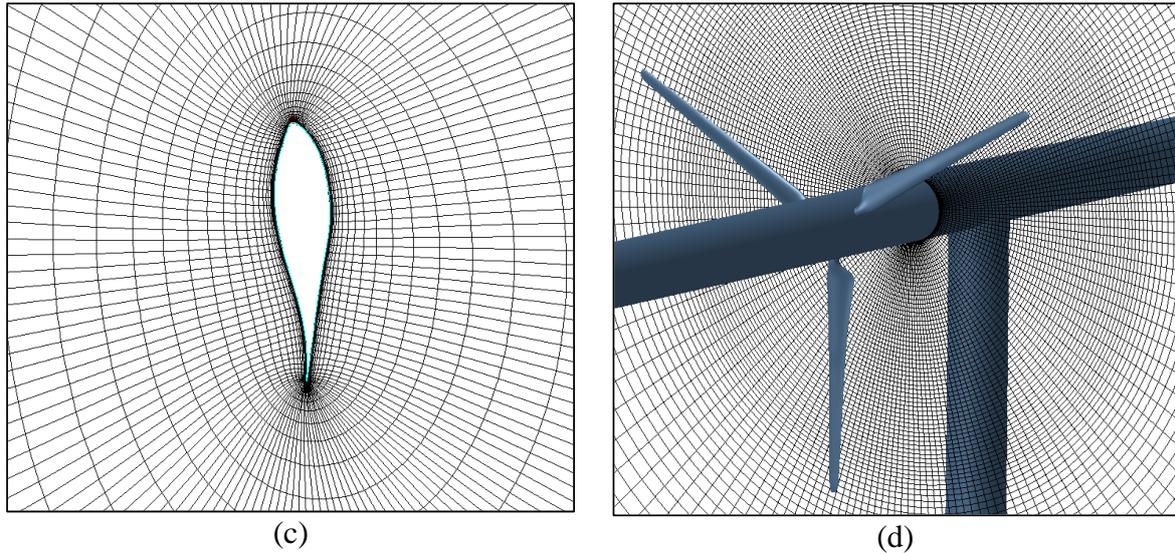
317 domain with a single blade and 7.5 million grid points in the tower domain. Therefore, a total
 318 of 16.5 million grid points are required for the frequency domain solution whereas 34.5 million
 319 grid points are required for the time domain solution. The generated computational domain and
 320 the grid are shown in Fig. 3.



(a)



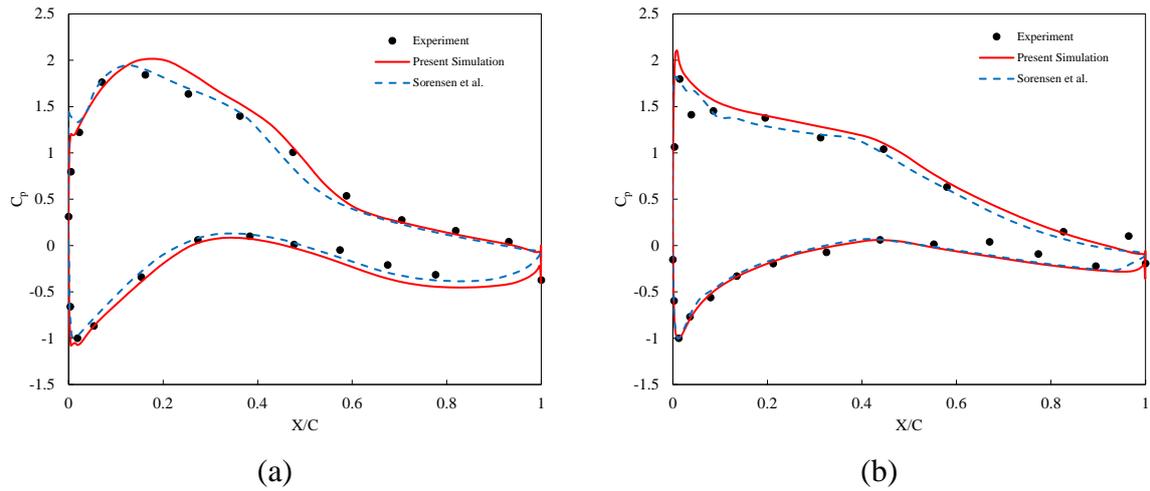
(b)



321
 322 Figure 3. The generated computational domain and grid: (a) Overall view of the computational
 323 domain, (b) details of boundary conditions, (c) blade-to-blade view of the mesh around the
 324 aerofoil and (d) rotor-stator interface.
 325

326 4. VALIDATION

327 Before performing simulations of multiple wind turbines, it is essential to ensure the accuracy
 328 of the numerical model employed in this study. To this end, the simulation of a single wind
 329 turbine is first performed, and the pressure coefficients are compared to the experimental data
 330 and the numerical data of Sorensen et al. [47]. Figure 4 shows the steady pressure coefficient
 331 distributions on the surfaces of the blade obtained at 60% and 82% of the blade span sections.
 332 It can be seen that the present numerical results at different span sections are in good agreement
 333 with the experiment and the reference simulation. More details and comparison of pressure
 334 coefficients at other blade sections can be found in [43,44]. Therefore, the employed CFD
 335 model is accurate enough to predict pressure distributions on the blade surfaces.

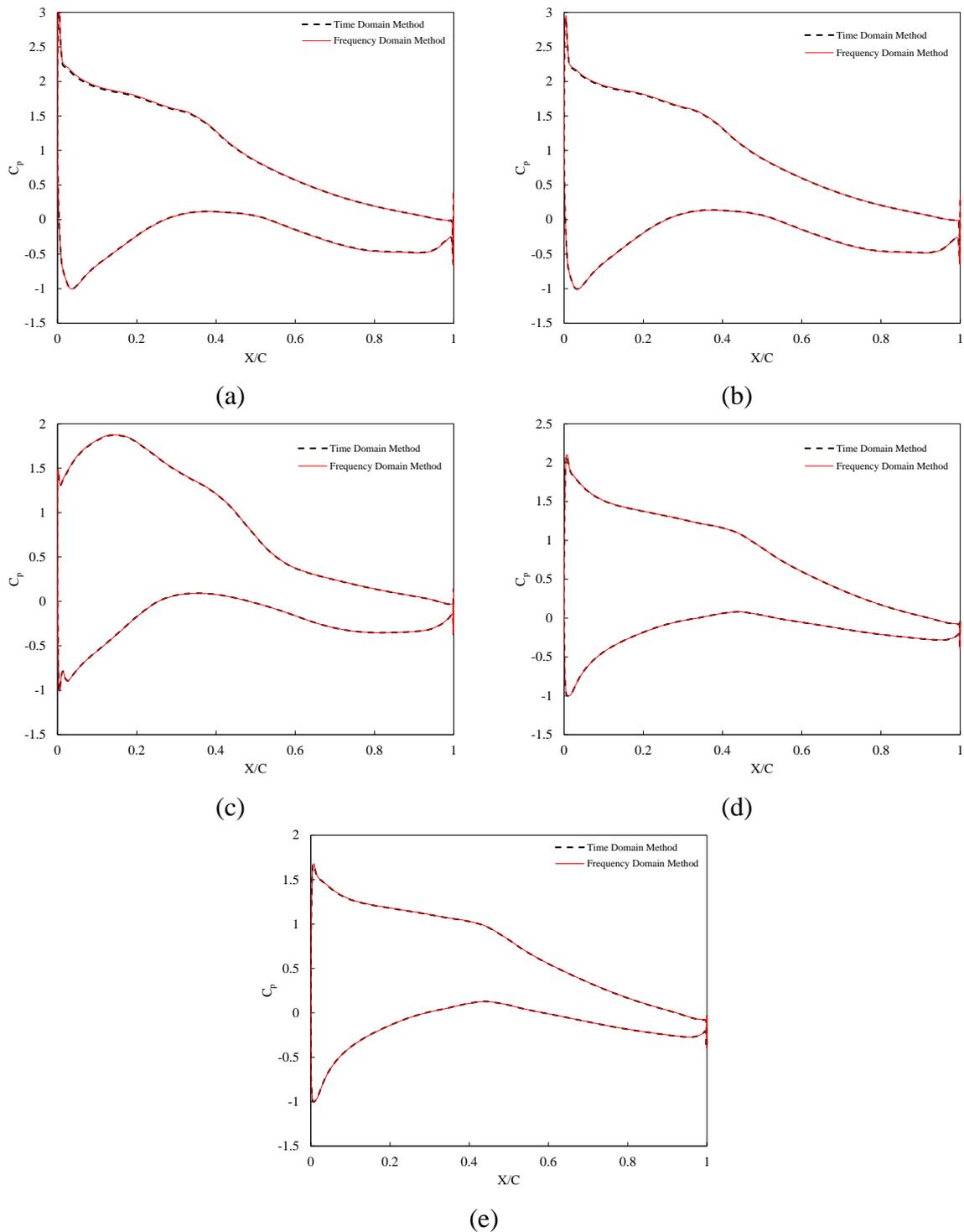


336
 337 Figure 4. Steady pressure coefficient distributions at (a) 60% and (b) 82% of the blade span
 338 obtained from the experiment, the reference simulation of Sorensen et al. [46] and the present
 339 simulation.
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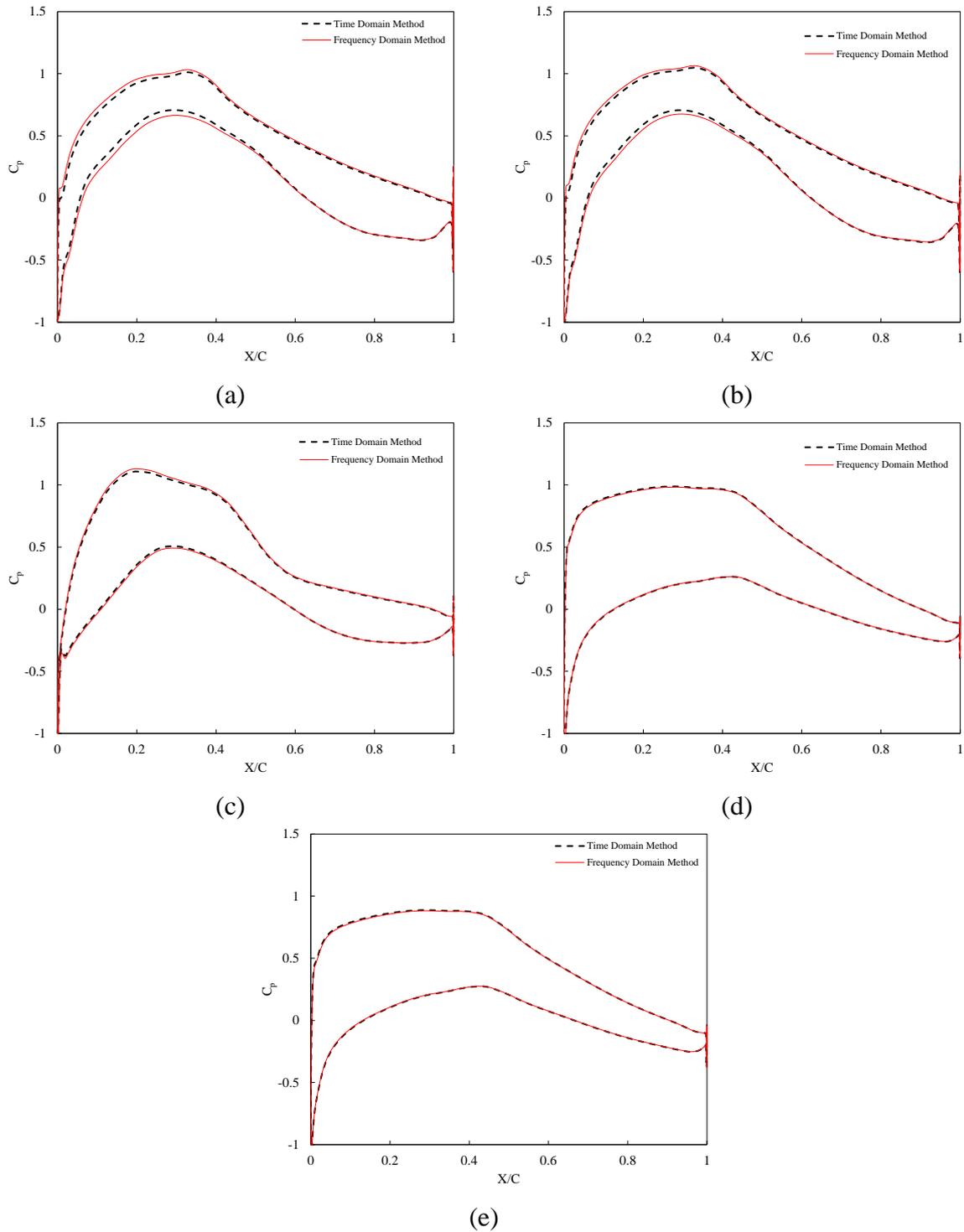
341 Figure 5 shows the comparison of the time-averaged pressure coefficient on the blade surfaces
 342 of the upstream wind turbine between the proposed frequency domain solution method and the
 343 time domain solution method based on the case in which the downstream wind turbine is placed
 344 at 2D behind the upstream wind turbine. The results are extracted at 25%, 30%, 50% 90% and
 345 95% of the blade span sections. As seen, the results of the frequency domain method are in
 346 excellent agreement with the time domain method at different span sections.

347
 348 Furthermore, Fig. 6 presents the variation of the time-averaged pressure coefficient on the blade
 349 surfaces of the downstream wind turbine at different span sections obtained from both time
 350 domain and frequency domain methods. Likewise, the results are obtained at different sections
 351 of the blade. As shown, the results from both methods are close to each other at all sections of
 352 the blade including 25% and 95% span sections, representing the bade root section and the tip
 353 section, respectively, where the flow is complex, which becomes problematic for the numerical
 354 methods. Therefore, it can be concluded that the frequency domain solution method accurately
 355 predicted pressure distributions on the surfaces of the blade of both upstream and downstream
 356 turbines. Contrary to the upstream turbine, significant deviations on the pressure distributions

357 on the blade surfaces are observed at different sections, which is mainly due to the effect of the
358 wake generated from the upstream wind turbine.



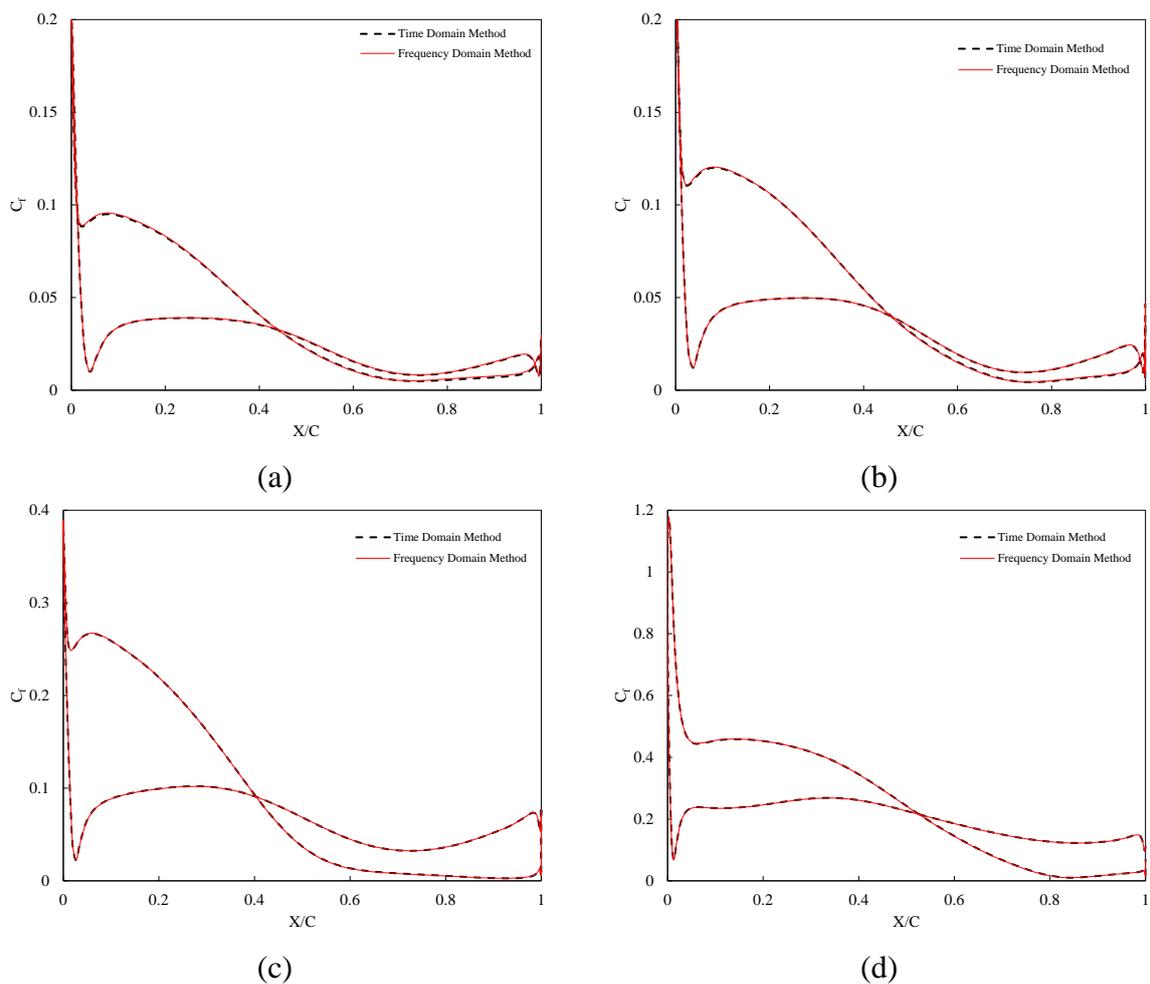
359
360 Figure 5. Time-averaged pressure coefficient distributions at (a) 25%, (b) 30%, (c) 50%, (d)
361 90% and (e) 95% of the blade span of the upstream wind turbine obtained from the time domain
362 method and the frequency domain method.
363

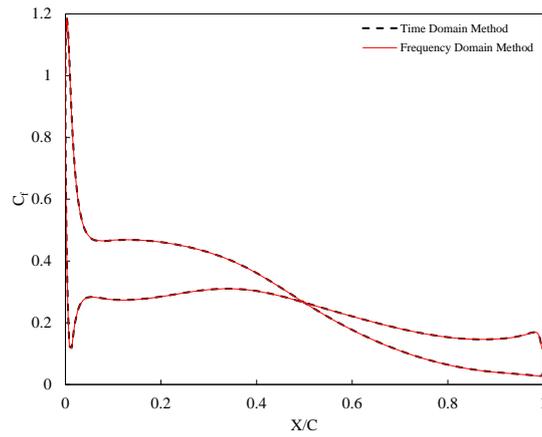


364
 365 Figure 6. Time-averaged pressure coefficient distributions at (a) 25%, (b) 30%, (c) 50%, (d)
 366 90% and (e) 95% of the blade span of the downstream wind turbine obtained from the time
 367 domain method and the frequency domain method.
 368

369 The comparison between the time domain solution method and the frequency domain solution
 370 method on predicting the skin friction coefficient distributions on the blade surfaces of the

371 upstream wind turbine and downstream wind turbine at the separation distance of 2D are
 372 presented in Figs. 7 and 8, respectively. Similar to pressure coefficients, the results are provided
 373 at different blade span sections, including 25%, 30%, 50%, 90% and 95% of the blade span.
 374 Likewise, the skin friction coefficients at different sections of the blade of both upstream and
 375 downstream wind turbines obtained from the frequency domain method are close to that of the
 376 typical time domain method. It is understood that the flow behaviours in the blade root region
 377 and the blade tip region are sometimes difficult to be accurately predicted by the numerical
 378 models due to the complex flow nature. However, it is seen that the results at all sections
 379 including 25% and 95% span sections obtained from both methods are in a good agreement,
 380 which indicates that the frequency domain method is accurate enough for the prediction of the
 381 aerodynamic parameters.

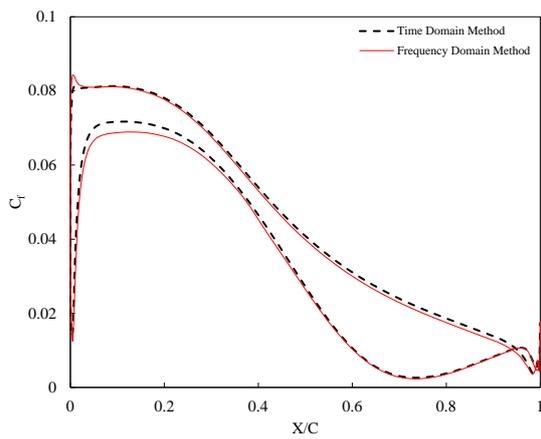




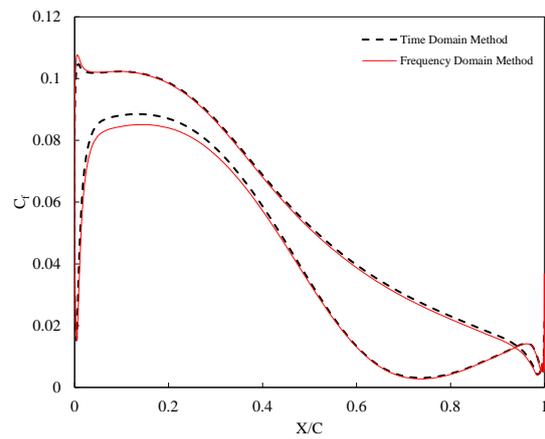
(e)

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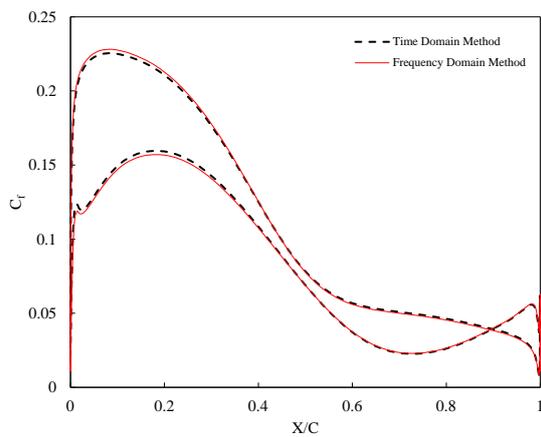
Figure 7. Skin friction coefficient distributions at (a) 25%, (b) 30%, (c) 50%, (d) 90% and (e) 95% of the blade span of the upstream wind turbine obtained from the time domain method and the frequency domain method.



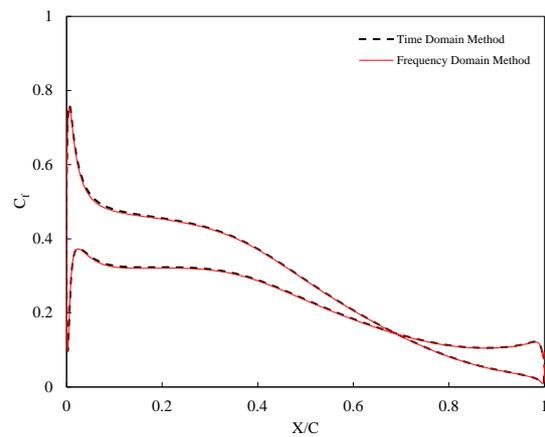
(a)



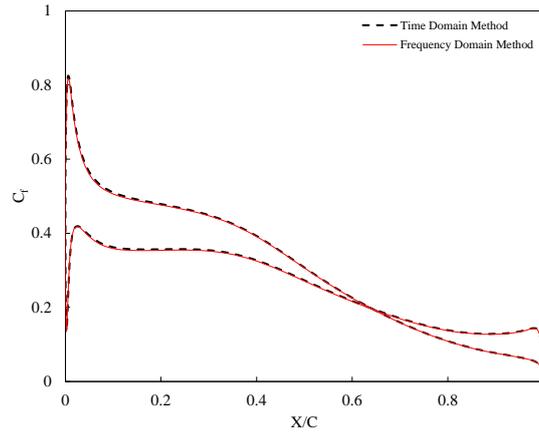
(b)



(c)



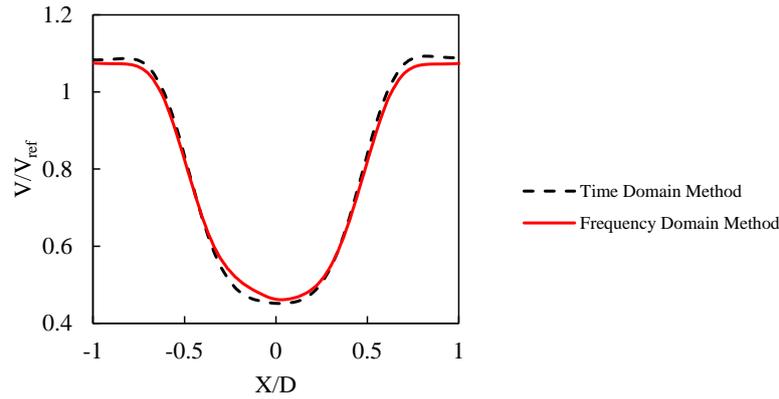
(d)



(e)

387
 388 Figure 8. Skin friction coefficient distributions at (a) 25%, (b) 30%, (c) 50%, (d) 90% and (e)
 389 95% of the blade span of the downstream wind turbine obtained from the time domain method
 390 and the frequency domain method.
 391

392 Figure 9 demonstrates the comparison between the frequency domain method and the time
 393 domain method for the dimensionless wake profile extracted at 1D before the downstream wind
 394 turbine, on the horizontal plane at the blade mid-span section. The wake profiles are shown for
 395 a distance of 1D to each side from the rotor centre. Slight deviations are observed between the
 396 two methods; however, the differences are very small, and the results obtained are in good
 397 agreement. The wake profile is calculated based on the variations of the velocity magnitude
 398 over the reference inflow velocity (V/V_{ref}). It is seen that the lowest peak of the wake occurs
 399 near the $X/D=0$, which is at the rotor centre, and it has a symmetrical profile on both sides.
 400 Consequently, it can be deduced that the numerical model employed in the present study is able
 401 to capture the unsteady flow and predict the wake accurately. This also indicates that the flow
 402 variables are exchanged correctly at the interface between the rotating and stationary domains.
 403



404

405 Figure 9. Wake profiles extracted at one rotor diameter before the downstream wind turbine
 406 obtained from the time domain method and the frequency domain method.

407

408 In-depth discussions on the effect of the upstream wind turbine on the downstream one will be

409 presented in the next section. The results show that not only the proposed frequency domain

410 solution method can capture the unsteady flow and calculate flow parameters accurately but

411 also the rotor-stator interface has been applied correctly as the results are in close agreement

412 between the two methods for both wind turbines. In order to highlight the advantage and the

413 capability of the frequency domain method and also for a direct comparison between the two

414 methods, the computational costs are compared for a period of an unsteady solution on a single

415 CPU with a 3.40 GHz Intel (R) Core (TM) i5-7500 CPU. For the time domain solution, both a

416 dual time-stepping method and a time-consistent multigrid method are employed for an

417 effective and efficient computation. It has been proved that these methods can accelerate the

418 computation. The simulation using the frequency domain method takes 6 hours whereas that

419 of the time domain method takes 200 hours even with an efficient computation. The required

420 numbers of period for an unsteady solution depends on the rotational speed and the distance

421 between the two turbines. However, with a frequency domain solution method, the unsteady

422 perturbations are computed based a period of the unsteady flow and the solution can be

423 reconstructed in time to have the flow solution in time history. Therefore, the computational

424 efficiency of the proposed frequency domain solution technique is considerable even when

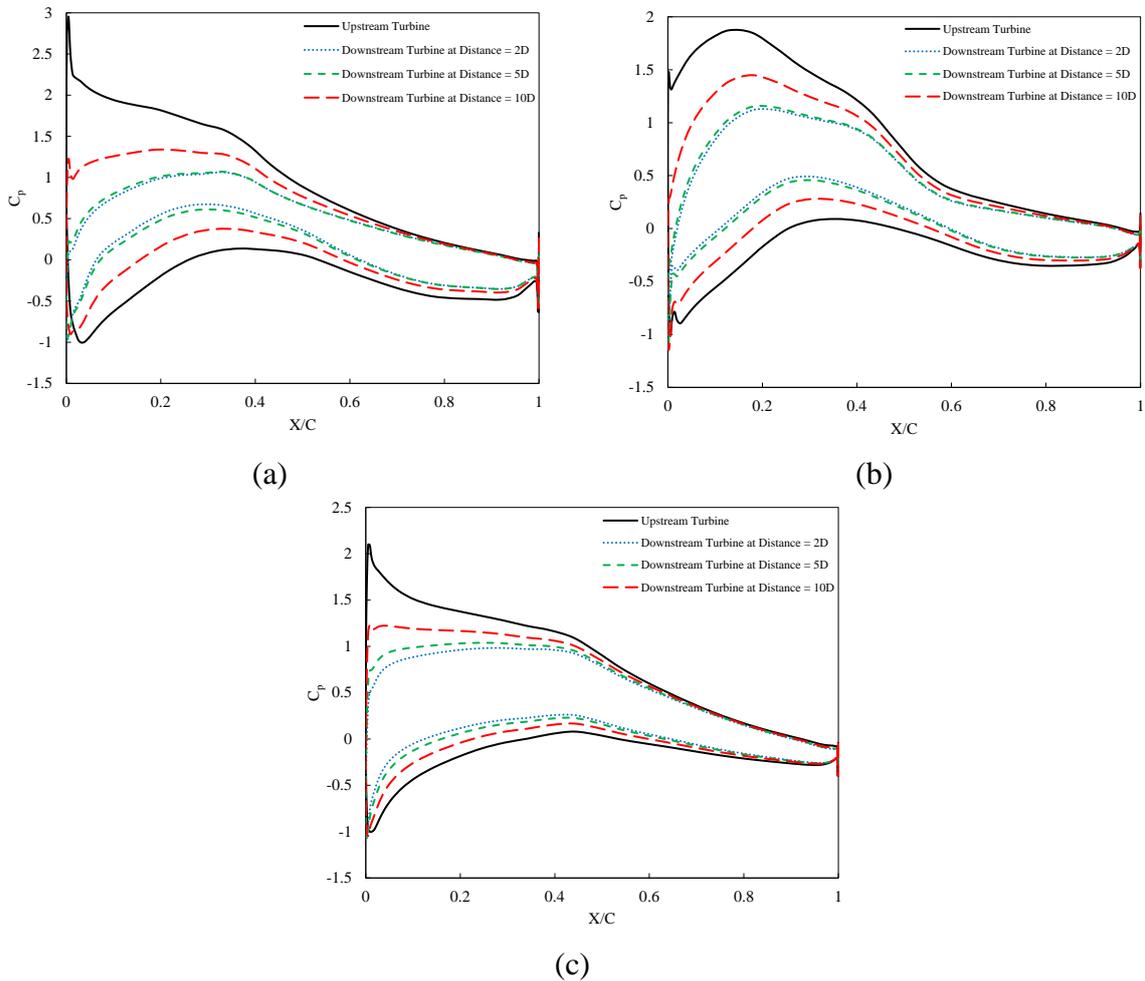
425 using a single CPU, and simulations of multiple wind turbines can be performed efficiently
426 with this method. Therefore, it is concluded that the frequency domain solution method can be
427 reliably utilised for further simulations of wind turbines in arrays by varying the distance
428 between the two turbines.

429

430 **5. RESULTS AND DISCUSSIONS**

431 Figure 10 compares the time-averaged pressure coefficients obtained from the upstream wind
432 turbine and the downstream wind turbine using different separation distances. The black line
433 represents the pressure coefficient from the rotor blades of the upstream wind turbine whereas
434 the rest of them are from that of the downstream wind turbine at different separation distances.
435 The effect of the wake from the upstream wind turbine on the downstream one can be seen at
436 all distances. The impact is much higher and more significant at the separation distances of 2D
437 and 5D. This indicates that the separation distance of 5D is not far enough for the downstream
438 wind turbine to avoid pressure losses if the downstream wind turbine is to be placed in the
439 wake region of the upstream one. The flow recovers beyond the distance of 5D and the
440 downstream wind turbine is less affected by the upstream one at 10D distance. However, there
441 is still a noticeable impact from the upstream wind turbine even at this far distance. The results
442 illustrate that the pressure coefficient on the blade surfaces of the downstream turbine at
443 $X/C=0.2$ is increased by approximately 30% by raising the distance from 2D to 10D at 50%
444 span. Strong deviations in pressure distributions are detected near the leading edge of the blades
445 whereas a similar trend is noticed after $X/C=0.5$. These deviations are mainly caused by the
446 non-uniform inflow with lower velocity magnitude which alters pressure distributions near the
447 leading edge. This effect becomes much smaller at 10D distance where the flow is nearly
448 uniform again. These observations indicate that the effect of the upstream wind turbine can be

449 reduced by raising the distance from 5D to avoid significant pressure losses for the downstream
 450 wind turbine.



451
 452 Figure 10. Time-averaged pressure coefficient distributions at (a) 30%, (b) 50% and (c) 90%
 453 of the blade span of the upstream wind turbine and the downstream wind turbines at different
 454 separation distances.
 455

456 Unsteady pressure distributions on the blade surfaces of both upstream and downstream wind
 457 turbines can be visualised in Figs. 11-12. Unsteady pressure distribution can be decomposed
 458 into the time-averaged value and amplitude of unsteady fluctuations as expressed in:

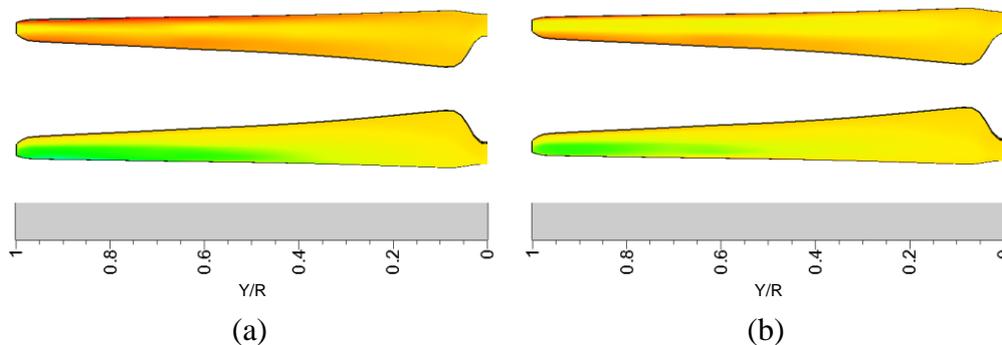
459

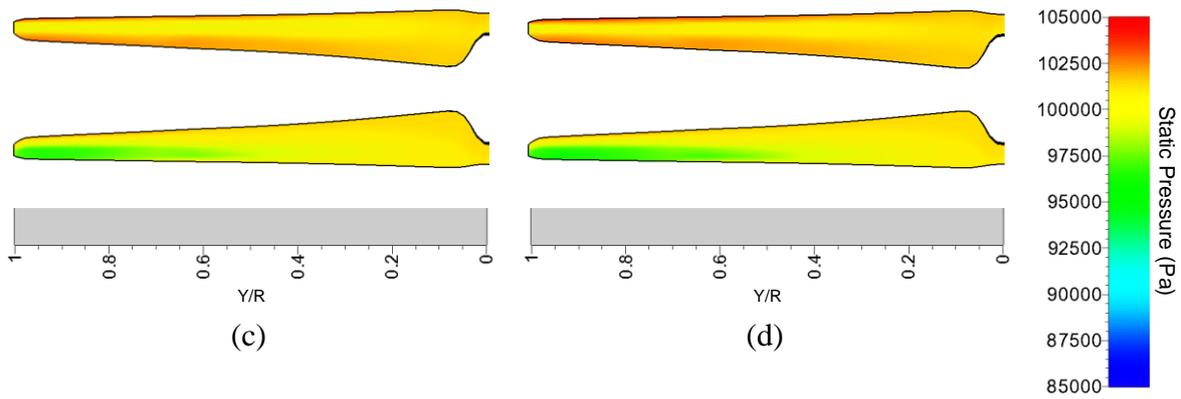
$$460 \quad P = \bar{P} + P_A \sin(\omega t) + P_B \cos(\omega t) \quad (6)$$

461

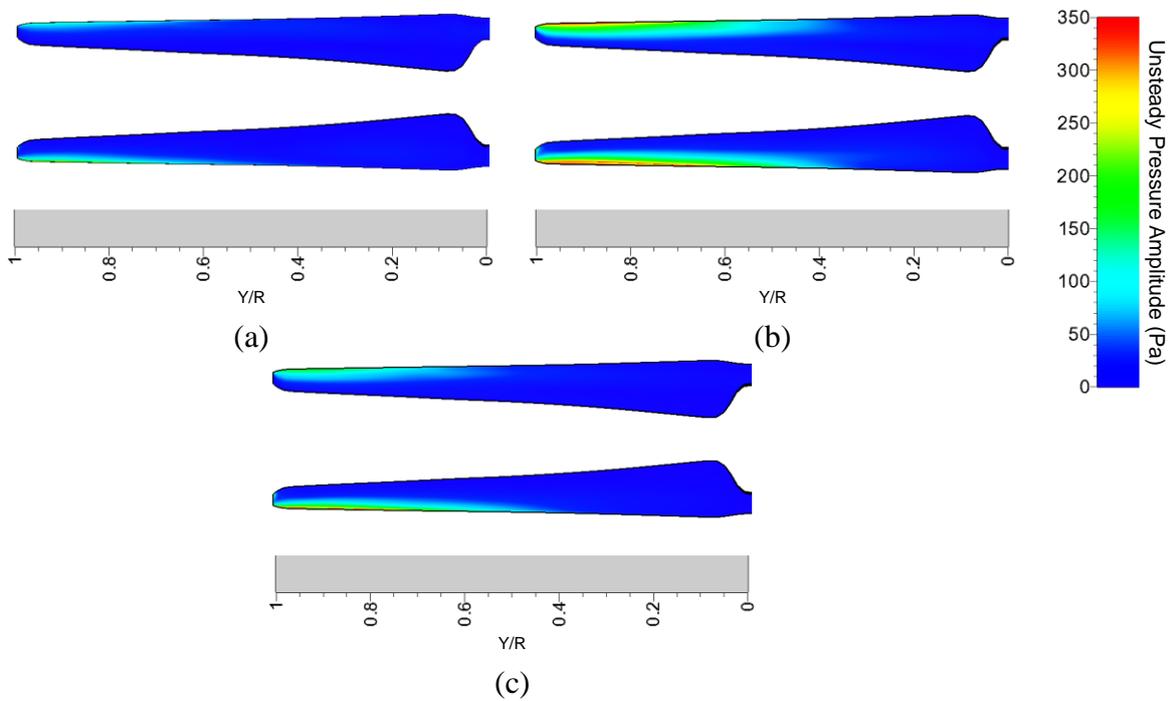
462 where \bar{P} is the time-averaged pressure and P_A and P_B are Fourier coefficients. Unsteady
 463 pressure amplitude can be defined as: $\tilde{P} = \sqrt{P_A^2 + P_B^2}$. Figure 11 presents the time-averaged
 464 pressure contour on the pressure and suction surfaces of both wind turbines. On the blade of
 465 the upstream wind turbine, higher pressure distributions are seen on the pressure surface near
 466 the leading edge and the trailing edge whereas lower pressure distributions are observed on the
 467 suction surface from approximately 40% of the blade span. In the case of downstream wind
 468 turbines, pressure distributions on the blade surfaces are lower due to the wake of the upstream
 469 wind turbine. At the separation distances of 2D and 5D, the pressure is higher near the trailing
 470 edge than the leading edge. Lower pressure field is developed within 60% - 100% of the blade
 471 span sections on the suction surface, which is shorter than that of the upstream wind turbine.
 472 In the case of 10D separation distance, the pressure seems to recover as it is far away from the
 473 upstream wind turbine. On the pressure surface, the pressure is higher near both leading and
 474 trailing edges than that of the 2D and 5D cases whereas the low-pressure field starts to occur
 475 at approximately 55% of the blade span section, which is closer to that of the upstream wind
 476 turbine. However, the effect of the upstream wind turbine is still present by the noticeable
 477 amount even at this far distance as pressure distributions on the blade surfaces of the
 478 downstream wind turbine are lower.

479





480
 481 Figure 11. Time-averaged pressure (\bar{P}) distributions on the pressure surface (*upper*) and the
 482 suction surface (*lower*) of the blade from (a) the upstream wind turbine, (b) the downstream
 483 wind turbine at the separation distance of 2D (c) the downstream wind turbine at the separation
 484 distance of 5D and (d) the downstream wind turbine at the separation distance of 10D.
 485



486
 487 Figure 12. Unsteady pressure amplitude (\tilde{P}) distributions on the pressure surface (*upper*) and
 488 the suction surface (*lower*) of the blade from (a) the downstream wind turbine at the separation
 489 distance of 2D (b) the downstream wind turbine at the separation distance of 5D and (c) the
 490 downstream wind turbine at the separation distance of 10D.

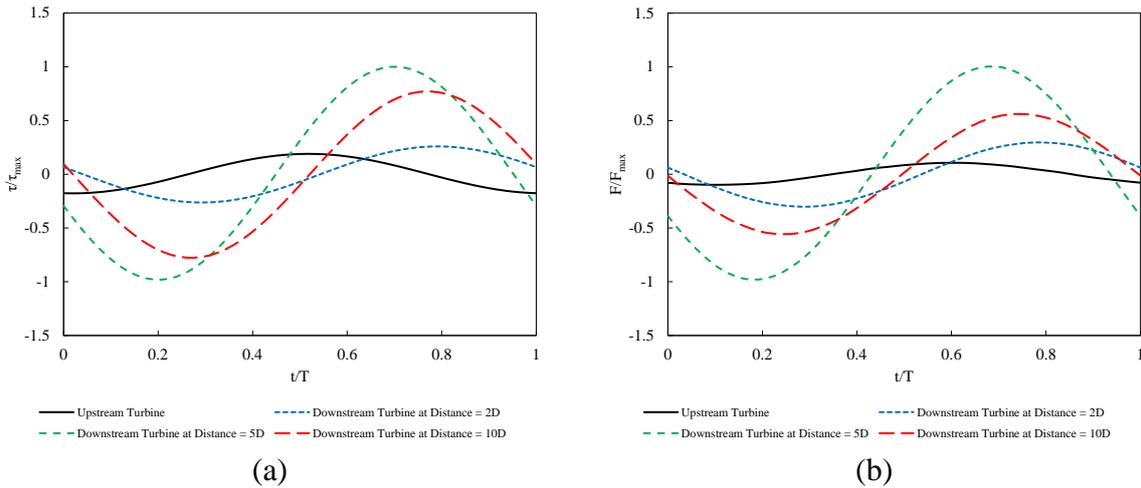
491 Figure 12 depicts the unsteady pressure amplitude contours on the pressure and suction surfaces
 492 of the downstream wind turbine placed at different separation distances behind the upstream
 493 wind turbine. The amplitudes of unsteady fluctuations are only visible in the cases of the
 494 downstream turbine. At the separation distance of 2D, some unsteady pressure fluctuation is
 495 seen near the blade tip on both surfaces. However, compared to the 2D separation distance

496 case, the amplitude of the unsteady pressure is much higher at 5D separation distance. Unsteady
497 pressure distributions are also seen on both surfaces, around the leading edge, starting from
498 approximately 40% of the blade span section. In the case of 10D separation distance, the
499 unsteady pressure fluctuations tend to decrease as it is lower than that of the 5D separation
500 distance case. However, the amplitude and fluctuations are still higher than the 2D separation
501 distance case. These results and observations show that the far wake imposes more turbulence
502 and flow disturbances, and it has more significant impact on the unsteady pressure distributions
503 on the blade surfaces of the downstream wind turbine than the near wake as the amplitude is
504 maximum at 5D separation distance and it tends to reduce beyond this distance.

505

506 Pressure distributions on the blade surfaces are directly related to the aerodynamic loads acting
507 on the blade surfaces. The aerodynamic loads applied on the blade surfaces are provided in
508 terms of torque and force profiles. The force profiles are evaluated based on the axial thrust.
509 Figure 13 shows the torque and force coefficient profiles acting on the surfaces of the upstream
510 wind turbine and downstream one at different separation distances. The coefficients, denoted
511 by τ/τ_{max} for torque and F/F_{max} for force, are defined as: (*Torque on Blade-Average Torque on*
512 *Blade*)/(*Maximum Torque on Blade*) and (*Force on Blade-Average Force on Blade*)/(*Maximum*
513 *Force on Blade*), respectively. Both torque and force profiles are plotted with respect to the
514 transient dimensionless computation time for one complete rotor revolution. The results show
515 that, in the case of the upstream wind turbine, the force profile is nearly uniform with some
516 fluctuations whereas the deviation of the torque profile is noticeably stronger. However,
517 harmonic force profiles are detected for both torque and force profiles on the blade of the
518 downstream wind turbines. The amplitudes of the torque and force coefficients are intensified
519 by 75% and 70%, respectively, when increasing the separation distance from 2D to 5D and
520 then they tend to reduce by 20% and 50%, respectively, when increasing the distance between

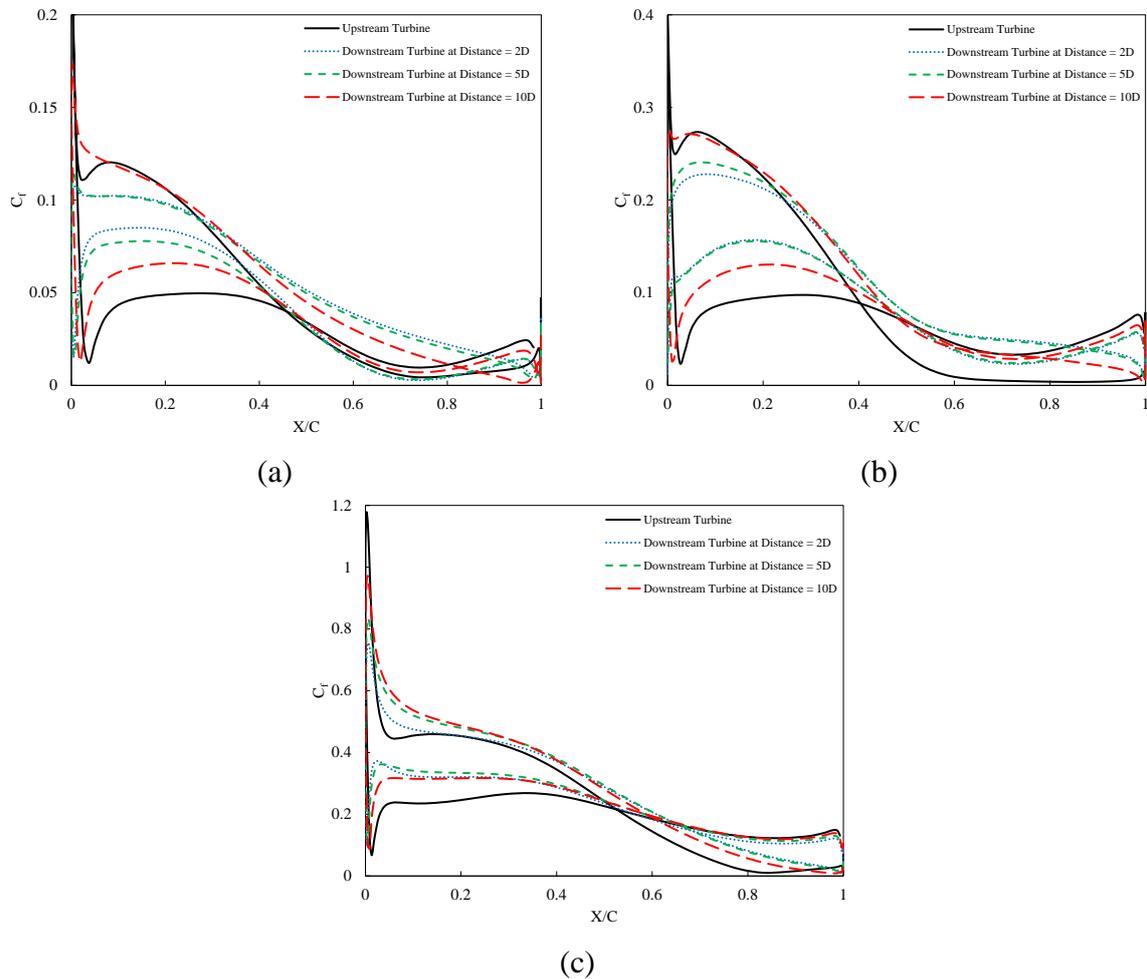
521 the wind turbines from 5D to 10D. It is noted that the difference in amplitude between the 5D
 522 and 10D cases is smaller for torque profiles than force profiles. In both cases, the aerodynamic
 523 loads acting on the blade surfaces are maximum at the 5D separation distance due to the flow
 524 turbulence and the far wake effect from the upstream wind turbine. These are consistent with
 525 the unsteady pressure distributions discussed in Fig. 12.



526 Figure 13. (a) Torque profile and (b) force profile applied on the blade surfaces obtained from
 527 the upstream wind turbine and the downstream wind turbines at different separation distances.
 528
 529

530 Figure 14 demonstrates the comparison of the skin friction coefficients on the blade surfaces
 531 of the upstream wind turbine and the downstream one placed at different separation distances.
 532 Similar to pressure coefficient distributions, the skin friction coefficients on the blade surfaces
 533 of the downstream wind turbine are most affected by the upstream wind turbine at the
 534 separation distances of 2D and 5D. However, it is less affected at the separation distance of
 535 10D as it is very far from the upstream wind turbine. At this distance, the wake generated from
 536 the upstream wind turbine recovers and the flow is nearly uniform again. This leads to a similar
 537 trend of skin friction coefficient distribution on the blade surfaces of the downstream wind
 538 turbine as that of the upstream turbine, but some noticeable variations and effects from the
 539 upstream turbine are still observed. The results show that the skin friction coefficient is the
 540 highest near the leading edge of the wind turbine blade due to the boundary-layer flow

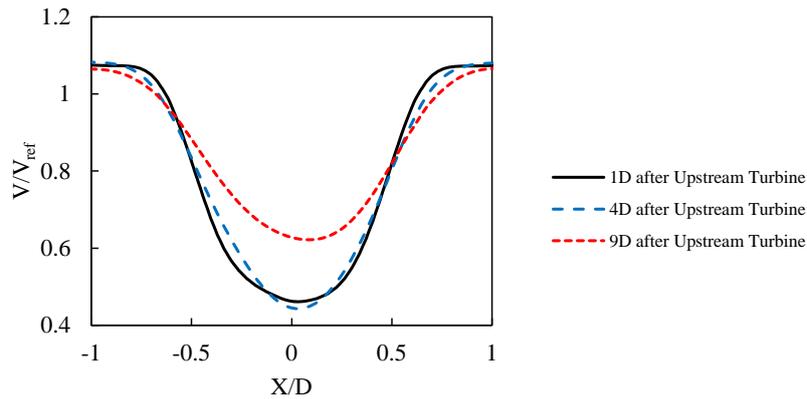
541 formation in this region. The fluctuations in the skin friction coefficient with respect to X/C
 542 are mainly related to the flow separation and recirculation over the suction surface of the blade.



543 Figure 14. Skin friction coefficient distributions at (a) 30%, (b) 50% and (c) 90% of the blade
 544 span of the upstream wind turbine and the downstream wind turbines placed at different
 545 distances behind the upstream turbine.
 546
 547

548 Figure 15 illustrates the instantaneous velocity profiles or wake profiles calculated at 1D before
 549 the downstream wind turbine from each case with different separation distances. By plotting
 550 the instantaneous velocity profiles, the behaviour of flow in both space and time (i.e., the
 551 velocity magnitude at different locations at a certain physical time) can be determined. The
 552 profiles are extracted on the horizontal plane at the blade mid-span section for a distance of 1D
 553 to each side from the rotor centre. These profiles demonstrate the wake profiles with respect to
 554 the distance from the upstream wind turbine as well as the inflow profile for the downstream

555 wind turbine. The $-0.5X/D$ to $0.5X/D$ region lies within the rotation of the blades and the
556 velocity in this region is reduced as the flow interacts with the blade which then captures the
557 energy from the wind. The results show that the amplitude of the wake profile becomes smaller
558 by increasing the distance from the upstream wind turbine. The minimum peak of the wake
559 occurs around the rotor centre; however, it is shifted towards $0.09X/D$ at $9D$ behind the
560 upstream wind turbine which is $1D$ before the downstream wind turbine at the separation
561 distance of $10D$. It was observed that the unsteady perturbations are maximum at the $5D$
562 separation distance, which is why a small shift in the profile is seen at $4D$ distance. It is also
563 noted that the wake beyond $5D$ distance gradually recovers; however, the unsteady
564 perturbations are still present with low intensity. Even at the distance of $10D$ which is far away
565 from the first turbine, where the flow seems to be more uniform, the perturbations and swirl
566 flow are not completely vanished. Furthermore, as a result of the recovery process from the
567 unsteady fluctuations, the inflow profile for the downstream turbine is not aligned with the
568 rotor. This is the reason why the minimum peak for the velocity profile at $9D$ distance shifts
569 slightly towards the positive side. The fact that the wake profiles at $4D$ and $9D$ distances shift
570 towards the positive side is related to the direction of the rotation of the rotor as both turbines
571 rotate in the same direction with the same rotational speed. These profiles indicate that the
572 wake from the upstream wind turbine is still significant at the distance of $4D$ behind the
573 upstream turbine. Therefore, a great impact on flow parameters was seen on the blade of the
574 downstream wind turbine placed up to $5D$ from the upstream turbine. However, at the distance
575 of $9D$, the amplitude of the wake profile reduces and the inflow velocity for the downstream
576 wind turbine tends to be closer to the reference velocity.

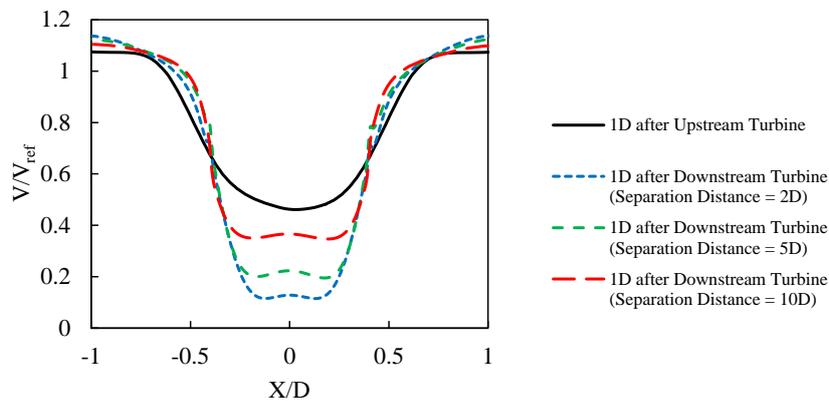


577

578 Figure 15. Wake profiles calculated at the distances of 1D, 4D and 9D behind the upstream
 579 wind turbine.
 580

581 Figure 16 demonstrates the wake profiles 1D after both upstream and downstream wind
 582 turbines with different separation distances. The profiles are extracted in a similar way to the
 583 previous profiles. This figure compares the near wake profiles after the flow interaction with
 584 each turbine. Compared to the upstream wind turbine, the velocity drop in the region of the
 585 blade rotation (i.e., $-0.5X/D$ to $0.5X/D$) is more sudden and significant in the cases of the
 586 downstream wind turbine and some variations are also seen near the rotor centre. The
 587 amplitudes of the wake profiles at the distance of 1D behind the downstream turbine reduce by
 588 increasing the distance between the two turbines. Large separation distance reduces the impact
 589 on the downstream turbine, and the magnitude of the wake generated from the downstream
 590 turbine at the separation distance of 10D is closer to that of the upstream turbine compared to
 591 other cases. Furthermore, it is noted that the inflow is completely uniform and steady at a
 592 reference velocity for the upstream wind turbine whereas the profile is parabolic with lower
 593 magnitude but stronger velocity distribution in the blade tip region for the downstream wind
 594 turbine. The inflow profiles for each downstream turbine case can be understood looking at the
 595 profiles presented in Fig. 15. For instance, the profile at 9D distance is the inflow profile for
 596 the downstream turbine at 10D distance in Fig. 15. By increasing the separation distance to
 597 10D, the intensity of the flow perturbation and recirculation are reduced, but their effects are

598 still present. This is the main reason why the wake profiles at 1D behind the upstream wind
 599 turbine and the downstream wind turbine are not similar. The impact of the swirl flow produced
 600 by the upstream wind turbine on the downstream one is significant at the separation distance
 601 of 2D, and it is reduced by increasing the distance to 10D, but it is not vanished. The main
 602 reasons for obtaining different shapes of the wake profile can be explained in similar way. The
 603 recirculation and flow perturbations generated from the upstream wind turbine alongside the
 604 lower velocity magnitudes due to the wakes will have noticeable impact on the amplitude of
 605 the wake profiles of the downstream one. The flow structures become more non-uniform by
 606 reducing the distance between the wind turbines from 10D to 2D.



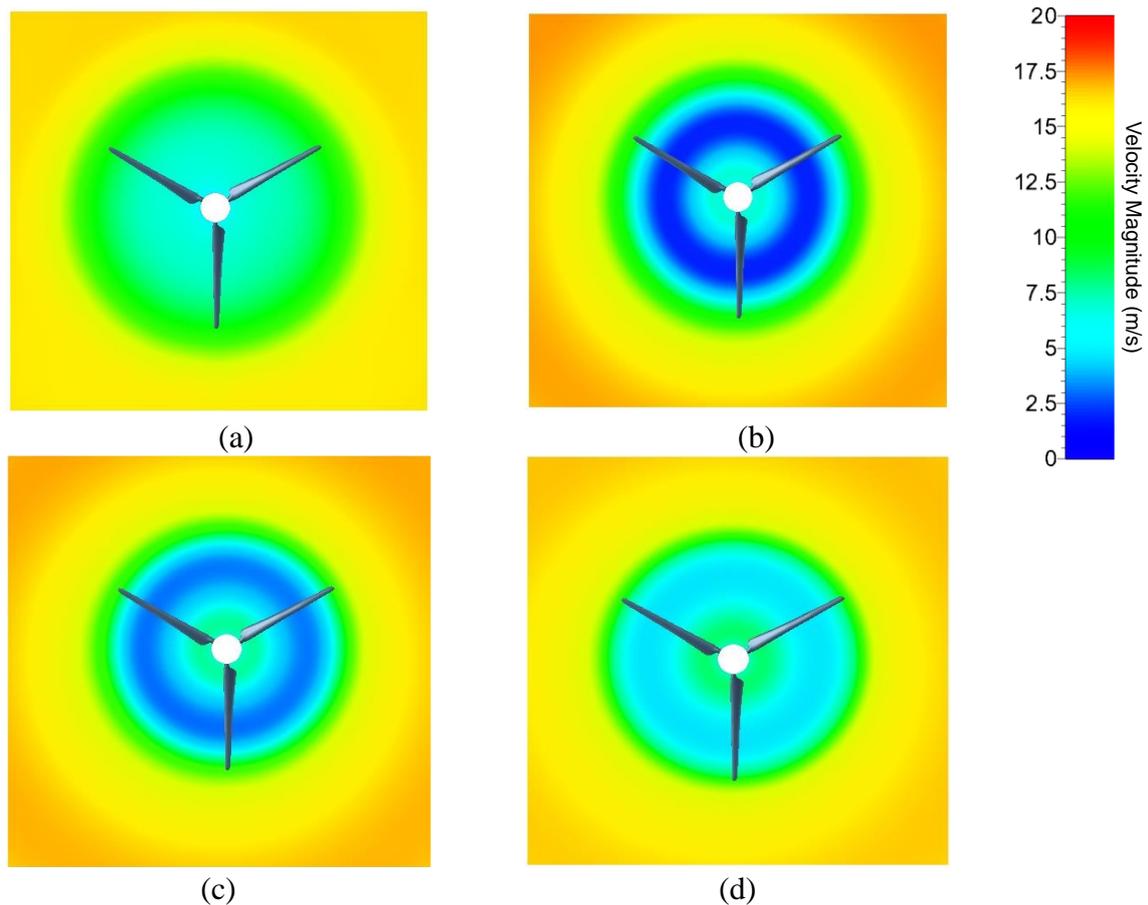
607

608 Figure 16. Wake profiles calculated at 1D after the upstream wind turbine and 1D after the
 609 downstream wind turbines at different separation distances.

610

611 The wake profiles, discussed in Fig. 16, can be better understood by looking at velocity
 612 contours extracted at 1D behind each turbine on the plane normal to the wind direction (See
 613 Figure 17). This figure particularly provides the flow information for visualisation of the flow
 614 condition at the same distance behind each turbine. It is seen that, in the case of the upstream
 615 wind turbine, the velocity distribution from the blade tip region to the blade root region is
 616 relatively linear whereas multiple layers of different velocity magnitudes are observed behind
 617 the rotors of downstream wind turbines. The velocity field is significantly affected after the
 618 flow interacts with the downstream wind turbine. The flow condition at the distance of 1D

619 behind the downstream turbine depends on the separation distance. The velocity magnitude
620 within the blade rotation, especially from approximately 40% to 80% span, is dramatically
621 reduced when the downstream turbine is closer to the upstream turbine and it rises as the
622 separation distance increases. Significant drops in the wake profiles, seen in Fig. 16, are
623 associated with this physical phenomenon.



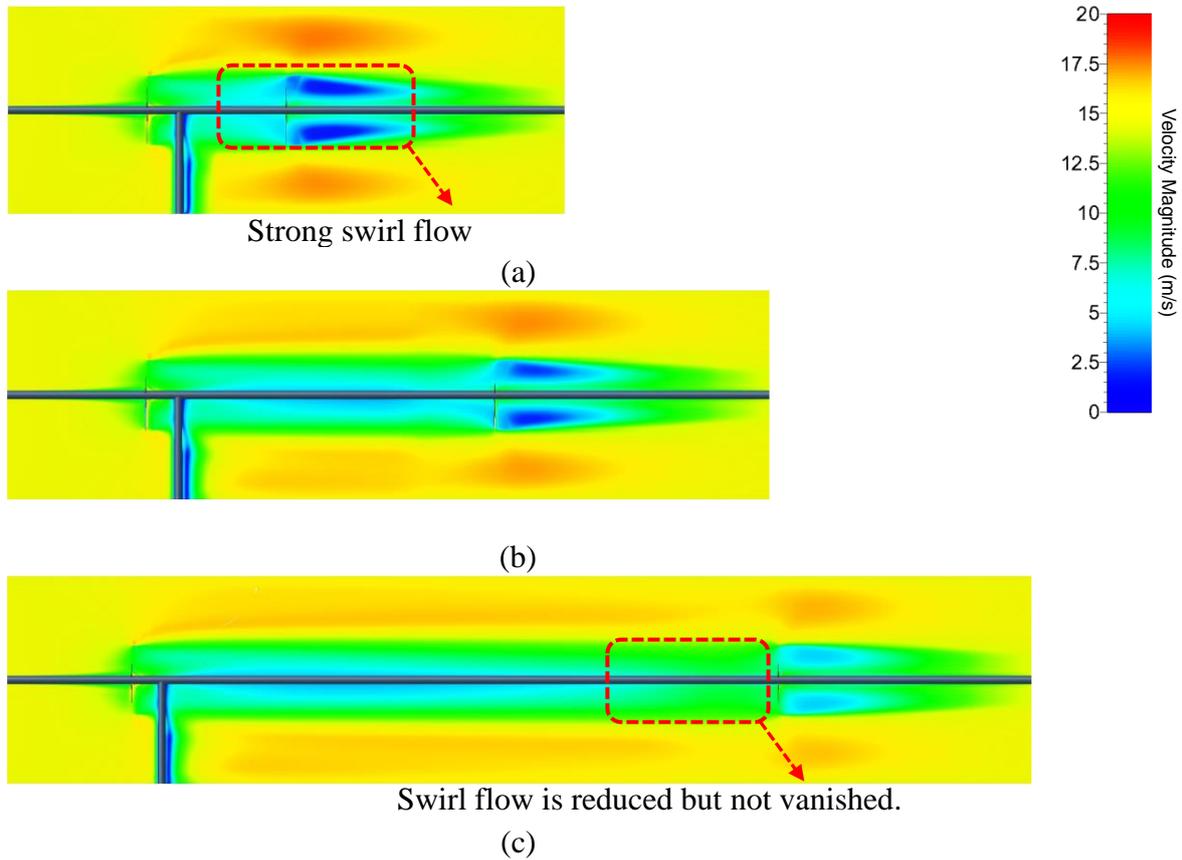
624
625 Figure 17. Velocity fields on the plane extracted at 1D behind (a) the upstream wind turbine,
626 (b) the downstream wind turbine with the separation distance of 2D, (c) the downstream wind
627 turbine with the separation distance of 5D and (d) the downstream wind turbine with the
628 separation distance of 10D.
629

630 The instantaneous velocity contours in the meridional view from different separation distance
631 cases are provided in Fig. 18 to visualise the flow field around and between the two wind
632 turbines. The uniform inflow velocity is dramatically reduced after the flow interaction with
633 the upstream wind turbine. In the case of 2D separation distance, the lower velocity field or the

634 wake and the swirl flow generated from the upstream turbine are still strongly present at the
635 distance of $2D$ behind the turbine where the downstream is located. As a result, the flow around
636 the downstream turbine is most dominated by the wake of the upstream turbine at this distance
637 and the velocity magnitude is further reduced behind the downstream turbine. In the case of
638 $5D$ separation distance, the wake from the upstream turbine gradually reduces but its influence
639 on the downstream turbine is still significant. However, at $10D$ separation distance, the lower
640 velocity field resulted from the flow interaction with the upstream turbine shrinks as the wake
641 recovers and the flow seems to be nearly uniform again. However, it should be noted that, as
642 discussed in Fig. 16, the swirl flow and unsteady perturbations from the upstream turbine are
643 still present at this distance. Despite the flow becoming more uniform at the $10D$ distance
644 compared to other cases, it is not entirely uniform yet as the velocity profile is parabolic shape.
645 It is seen that the magnitude of the inflow velocity is lower than the reference velocity;
646 however, it is larger than any other cases. As a result, the trends of the distributions of flow
647 parameters such as pressure on the blade surfaces on the downstream turbine are similar to that
648 of the upstream turbine with less magnitude due to lower inflow velocity. Furthermore, it is
649 also observed that the separation distance has an impact on the vortex generation and flow
650 circulation from the tips of the blades of the downstream wind turbine. The size of the tip vortex
651 structures around the downstream turbine at the separation distance of $2D$ is higher than any
652 other cases as it combines with those from the upstream turbine due to small separation
653 distance. As the separation distance increases, the vortex structures generated from the blades
654 of the upstream turbine continue to a certain distance before gradually losing its intensity, but
655 it is too far to reach the downstream turbine if the turbine is placed at $10D$ distance. As the
656 inflow for the downstream wind turbine is not uniform and identical as it is for the upstream
657 one, the wake behind the downstream turbine involves more turbulence and unsteadiness. The
658 flow recirculation generated from the upstream wind turbine also has an impact on the flow

659 disturbance and boundary-layer disruption near the blades of the downstream rotor. The flow
660 unsteadiness and the influences of the wakes on the flow field around the wind turbines are
661 considerable at different separation distances.

662

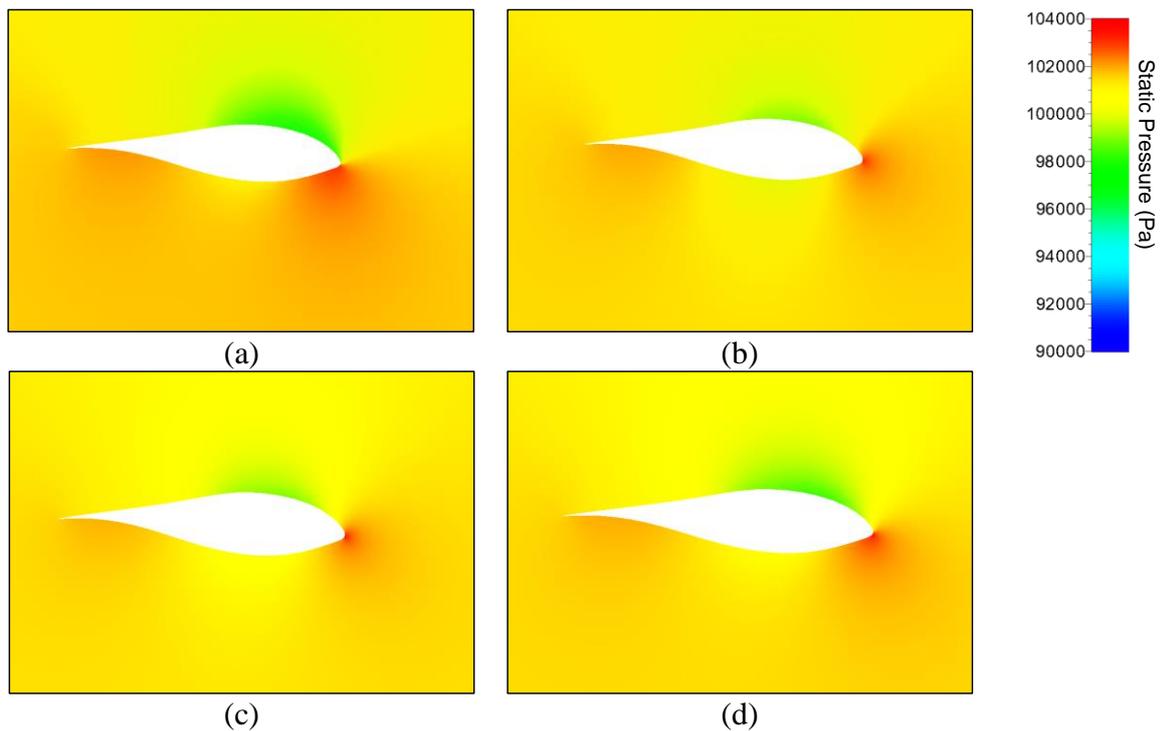


663 Figure 18. Velocity fields in the meridional view from the case of (a) separation distance = 2D,
664 (b) separation distance = 5D and (c) separation distance = 10D.
665
666

667 Pressure distributions around the aerofoil at the blade mid-span section from both wind turbines
668 are presented in Fig. 19. Generally, the pressure is higher on the pressure side and lower on the
669 suction side of the aerofoil, and the highest-pressure concentration is typically found near the
670 leading edge. In the case of the upstream wind turbine, the highest pressure is observed on the
671 pressure surface near the leading edge. The pressure distributions and the location of the
672 highest-pressure concentration around the aerofoil of the downstream wind turbine depend on
673 the separation distance from the upstream turbine. At the separation distances of 2D and 5D,

674 pressure distribution on both sides of the aerofoil is much lower than that of the upstream
675 turbine, and the highest pressure is seen at the leading edge. In the case of the 10D separation
676 distance, pressure distribution recovers as it is higher than 2D and 5D case but still lower than
677 that of the upstream wind turbine. However, the highest-pressure concentration point shifts
678 slightly towards the pressure surface.

679

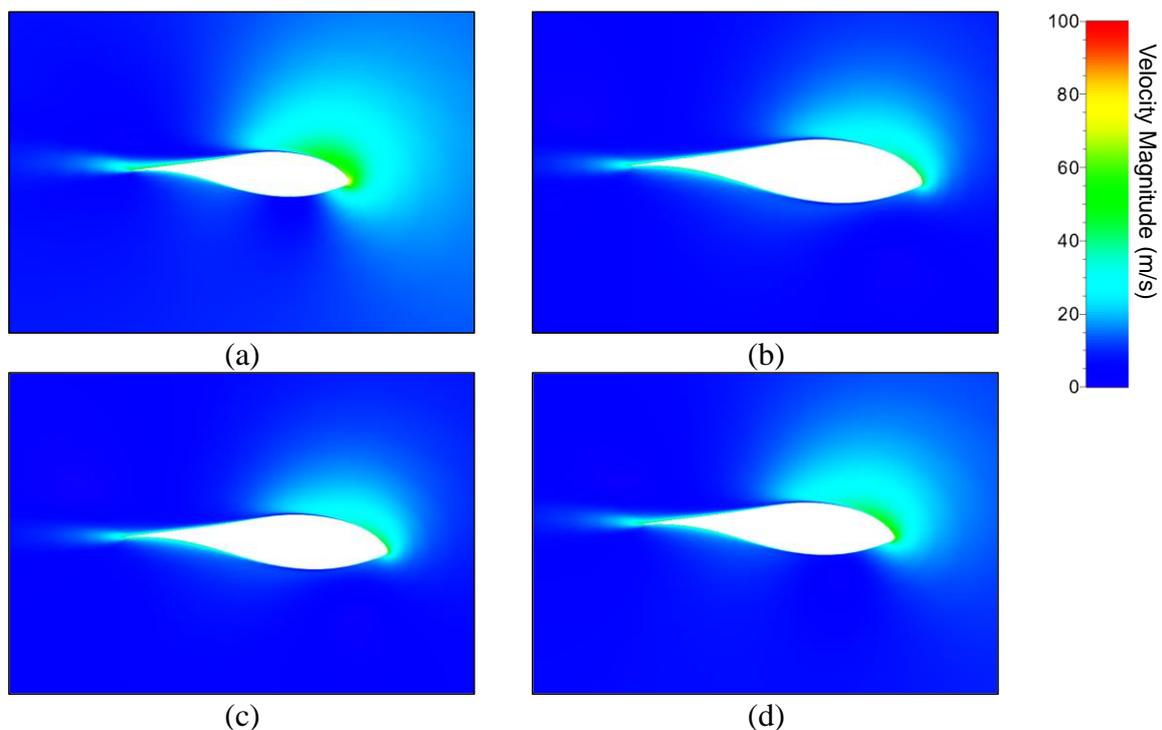


680

681 Figure 19. Pressure distributions around the aerofoil at the mid-span section of the blade of (a)
682 the upstream wind turbine, (b) the downstream wind turbine with the separation distance of 2D
683 (c) the downstream wind turbine with the separation distance of 5D and (d) the downstream
684 wind turbine with the separation distance of 10D.
685

686 Velocity distributions around the aerofoil at the blade mid-span section from both wind turbines
687 are shown in Fig. 20. In the case of the upstream wind turbine, the high-velocity concentration
688 is seen around the leading edge. After the relative velocity interacts with the blade aerofoil, the
689 velocity is distributed from the pressure surface near the leading edge over to the suction
690 surface up to the half of the chord length. A little flow separation from the suction surface is

691 also seen near the trailing edge. However, in the cases of the downstream wind turbine with
692 separation distances of 2D and 5D, the velocity magnitude is lower than that of the upstream
693 turbine and the velocity distribution is slightly different. The flow interaction point with the
694 blade aerofoil moves towards the leading edge and the velocity is distributed from the leading
695 edge over to the suction surface. The flow separation is very small compared to the upstream
696 turbine. At 10D distance, the velocity magnitude tends to increase again as the wake from the
697 upstream turbine recovers. The flow interaction point shifts a bit towards the pressure surface,
698 and the velocity distribution is similar, but with less magnitude, to that of the upstream turbine.
699

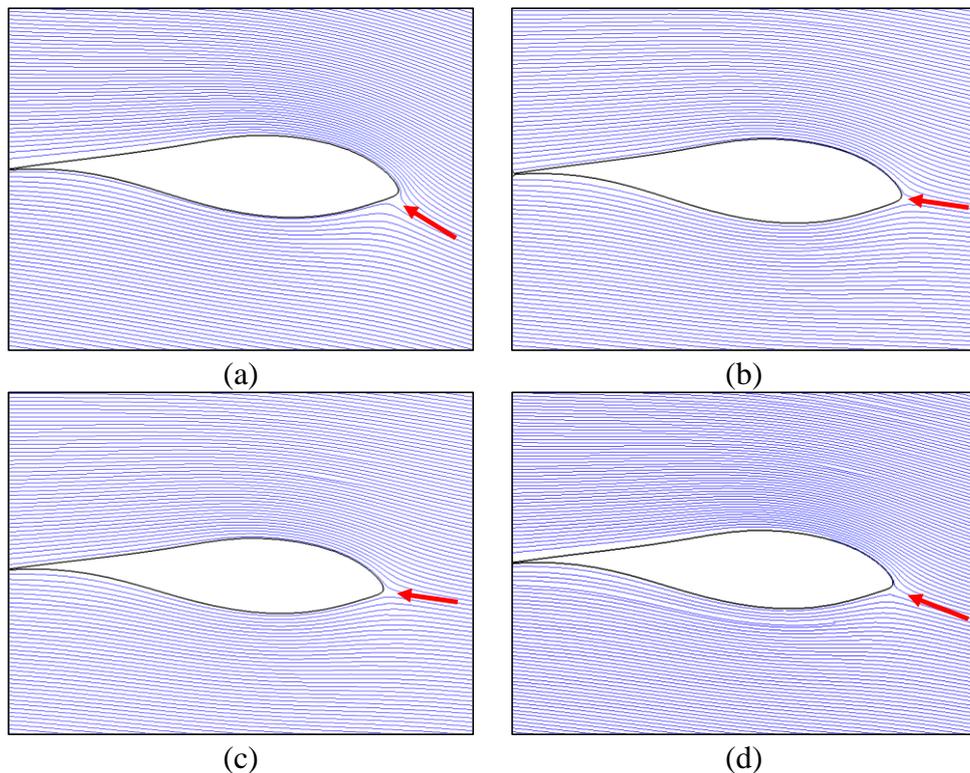


700

701 Figure 20. Velocity distributions around the aerofoil at the mid-span section of the blade of (a)
702 the upstream wind turbine, (b) the downstream wind turbine with the separation distance of 2D
703 (c) the downstream wind turbine with the separation distance of 5D and (d) the downstream
704 wind turbine with the separation distance of 10D.
705

706 Figure 21 shows the relative velocity streamlines around the aerofoil at the blade mid-span
707 section of both wind turbines. This can be visualised together with the velocity distribution,

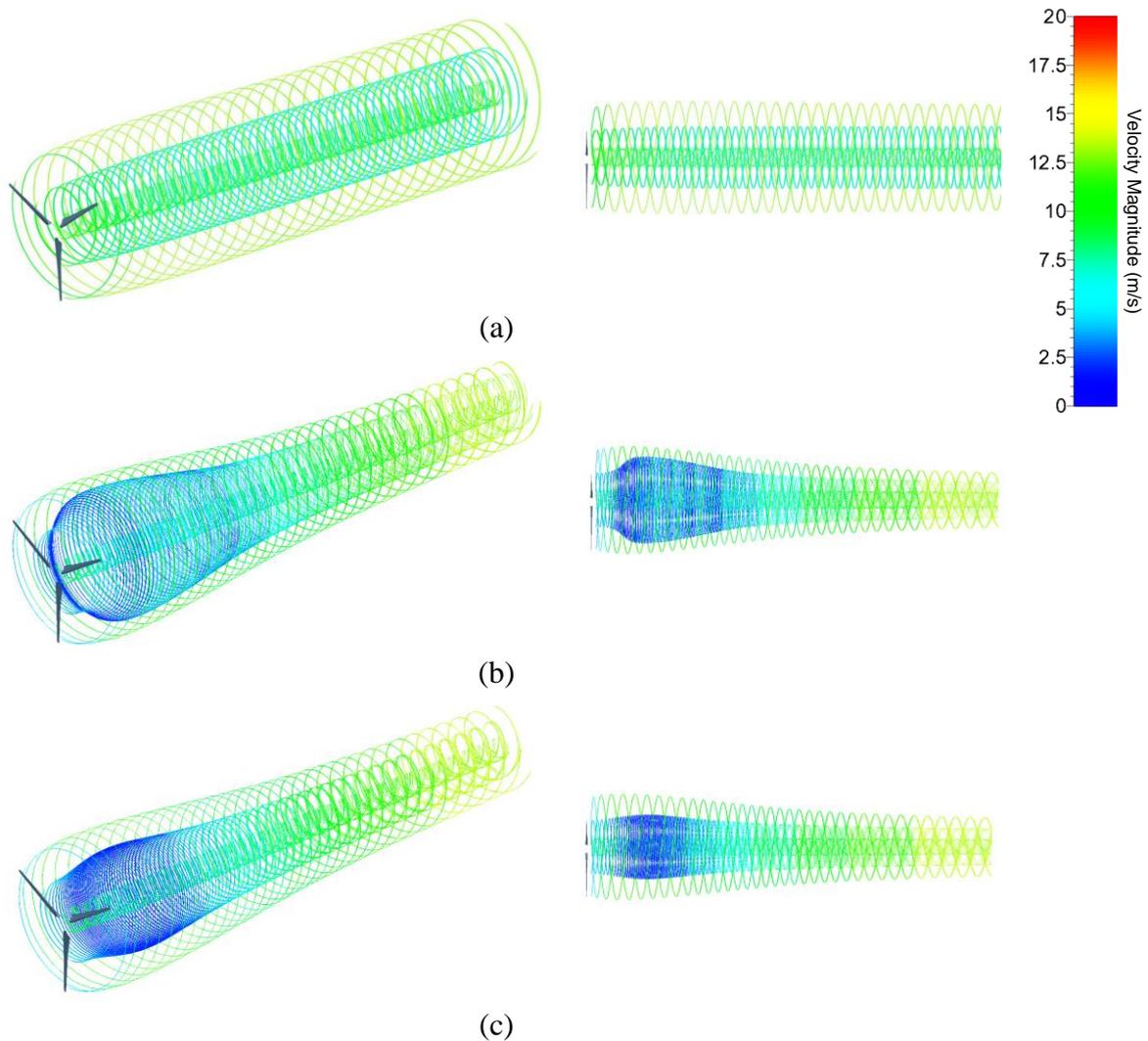
708 presented in Fig. 20. The direction of the relative velocity and the flow interaction with the
 709 aerofoil are different between the upstream and downstream wind turbines, and they also
 710 depend on the separation distances between the turbines. In the case of the upstream wind
 711 turbine, the angle of attack is larger than any other cases due to the uniform inflow. The wakes
 712 from the upstream wind turbine trigger flow disturbances, which changes the direction of the
 713 inflow for the downstream turbines. As a result, the angle of attack for the blade of the
 714 downstream wind turbine is smaller than that of the upstream turbine. The angle of attack is
 715 much smaller in the cases of 2D and 5D separation distance as the wake from the upstream
 716 wind turbine is significant at these distances and the flow around the downstream wind turbine
 717 is highly influenced by the wake. However, the angle of attack becomes larger and closer to
 718 that of the upstream turbine at 10D distance as the wake from the upstream turbine recovers
 719 and the inflow velocity for the downstream turbine is nearly uniform again.

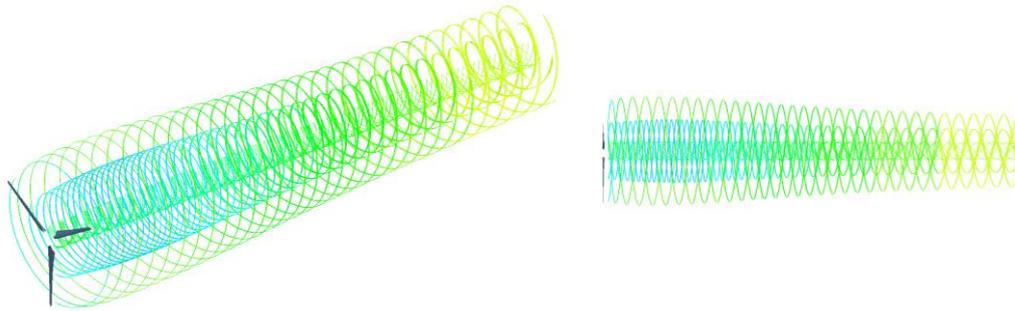


720
 721 Figure 21. Flow streamlines around the aerofoil at the mid-span section of the blade of (a) the
 722 upstream wind turbine, (b) the downstream wind turbine with the separation distance of 2D (c)
 723 the downstream wind turbine with the separation distance of 5D and (d) the downstream wind
 724 turbine with the separation distance of 10D.

725 Figure 22 illustrates the relative velocity streamlines in the rotating frame of reference for the
726 upstream and downstream wind turbines. In order to highlight the flow streamlines generated
727 from the upstream wind turbine alone, the streamlines from a single turbine case are presented
728 for the upstream turbine. The streamlines are provided up to 4D downstream of all turbines.
729 The three-dimensional view and meridional view are provided for better visualisation and
730 comparison between different cases. This figure clearly shows the effects of the upstream wind
731 turbine on the flow circulation and wake recovery process behind the downstream wind turbine
732 at different separation distances. Three layers of streamlines from the blade root region, the
733 blade mid-span region and the blade tip region where the tip vortex is generated are presented.
734 In the case of the upstream wind turbine, due to the uniform and steady inflow condition, a
735 recurring pattern of flow streamlines are generated from each layer of the rotor blades. It is also
736 seen that the streamlines are consistent up to 4D distance, which indicates that the downstream
737 wake is still strong. This is also consistent with the aerodynamic parameters of the blades of
738 the downstream turbine placed at 2D and 5D, where the flow is strongly influenced by the wake
739 of the upstream turbine. For the downstream wind turbines, the flow generated from the tip of
740 the blade slightly expands and then gradually becomes smaller as it moves further away from
741 the turbine whereas the flow from the blade root region is circulated around the hub. The major
742 difference between the downstream turbine cases can be seen in the streamlines generated from
743 the blade mid-span region. This is also consistent with the velocity contours presented in Fig.
744 17 in which it was seen that the velocity fields in the region of 40% - 80% span were
745 significantly affected. In the case of 2D separation distance, the circulation of the flow
746 streamlines from the blade mid-span region suddenly expands by a great extent after leaving
747 the blades which then gradually reduces. Compared to the 2D distance case, the expansion of
748 the flow streamlines is smaller in the 5D distance case whereas no noticeable expansion is
749 observed in the 10D distance case. It is noticed that the streamline behaviours from the 10D

750 distance case tend to be similar, but with some deviations, to those of the upstream turbine
751 because it is placed at a relatively far distance and the inflow condition is more uniform than
752 other two cases. In terms of the wake recover process for the downstream turbine, it is seen
753 that the recovery of the velocity magnitude is shorter in the 5D case than the 2D case. However,
754 in the case of 10D separation distance, the velocity field behind the rotor of the downstream
755 turbine remains relatively greater compared to other two cases due to the nearly uniform inflow,
756 which then gradually recovers to reach the reference velocity in the far downstream region.
757 Therefore, it is now evident that the flow unsteadiness and turbulence resulted from the
758 upstream wind turbine have a great influence on the vortex generation and the wake recovery
759 process of the downstream wind turbine.





(d)

760
761
762
763

Figure 22. Flow streamlines generated from (a) the upstream wind turbine, and the downstream wind turbines with the separation distances of (b) 2D, (c) 5D and (d) 10D.

764 6. CONCLUSIONS

765 In the present study, numerical simulations have been performed to investigate the effects of
766 separation distances between upstream and downstream wind turbines in arrays on the
767 aerodynamic performances and the flow field around the wind turbines. A novel frequency
768 domain solution method is employed for the first time to model the wind turbines in arrays as
769 a multi-stage turbine in a multi-stage configuration. Before investigating multiple wind
770 turbines, a single wind turbine was first modelled and validated against the experiment and the
771 reference simulation. Good agreements between the numerical results and the experimental
772 data are obtained. The proposed nonlinear frequency domain solution method was then applied
773 to the simulation of two turbines and validated against the conventional time domain solution
774 method based on the 2D separation distance case. The results obtained from both methods are
775 in excellent agreement and they are close to each other.

776

777 After the numerical model and method have been validated, the frequency domain method was
778 used for further investigations using different separation distances. It is found that pressure
779 coefficient and skin friction coefficient distributions on the blade surfaces of the downstream
780 wind turbine are significantly influenced by the wake of the upstream wind turbine. The effect
781 of the upstream wake is significant up to the separation distance of 5D and then it gradually

782 reduces. The far wake from the upstream turbine has more effect on the downstream turbine
783 than the near wake. The amplitudes of unsteady fluctuations including pressure and force
784 distribution on the blade surfaces are maximum at the separation distance of $5D$. The flow field
785 and wake from the upstream turbine gradually recover beyond the distance of $5D$ and the
786 aerodynamic performances of the downstream wind turbine tend to increase again.
787 Furthermore, flow visualisations show that the velocity field behind the downstream turbine is
788 most affected in the 40% - 80% span region of the blade rotation and the impact is more
789 significant with smaller separation distances. Therefore, it is certain that the downstream
790 turbine cannot be placed within $5D$ of the separation distance. Furthermore, according to [6],
791 the minimum spacing restriction of $5D$ is employed in most recent optimisation studies.
792 Furthermore, it is understood that the common practice for the placement of the downstream
793 wind turbine in most practical applications is around $7D$. Hence, a conclusion is drawn based
794 on the results obtained, the reference studies and the common practice that the separation
795 distance should be larger than $5D$, and it is recommended that the downstream wind turbine is
796 placed between $5D$ and $10D$ to reduce the effect of the upstream turbine as well as to optimise
797 the performances of the downstream turbine and the wind farm.

798

799 In terms of the computational cost, the frequency domain solution method can reduce the
800 computation time by one to two orders of magnitude compared to the time domain solution
801 method. Although only the rotor of the downstream turbine is considered in this study, further
802 turbines can be added, and more complex simulations can be performed due to the advantages
803 and capabilities of simulating a series of rotor-stator interactions with the proposed frequency
804 domain solution method.

805

806

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810

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